GEOMETRIC STRUCTURE AND CONVEX DECOMPOSITION OF U-POLYGONS Paolo Dulio

In a given space Y, the uniqueness problem of Geometric Tomography asks for the minimum number of radiographies needed for the unique determination of a geometric object in Y. Usually the problem is addressed to the class \mathcal{C}_Y of all convex bodies of Y. A crucial step is to highlight geometric structures linked to possible ambiguities in the reconstruction process.

If radiographies are performed through parallel X-rays in a set U of directions, the so called U-polygons come out, which are the convex counterpart of more general structures called switching components. Understanding their geometric structure often allow uniqueness results to be achieved. There are some geometric parameters which can help in such an investigation. For instance, in the Euclidean plane \mathbb{R}^2 , no U-polygons exist if U consists of 4 directions with transcendental cross-ratio ρ . This means that such a set of four directions uniquely determines a convex body in $\mathcal{C}_{\mathbb{R}^2}$ ([4]). The same is true for the class $\mathcal{C}_{\mathbb{Z}^2}$ if |U| = 7, or |U| = 4 and $\rho \notin \{2, 3, 4\}$, up to a reordering of the directions (see [3], and also [2] where a further geometric parameter is considered, namely the class of a U-polygon). Also, the presence of symmetry seems to be deeply related to the spread of ambiguities in the reconstruction processes. In this direction an important result has been achieved in [5], where switching components are characterized as the linear combination of switching element. When U-polygons are considered the role of convexity does not appear immediately. This is obtained in [1], where an alternative geometric approach leads to a kind of convex counterpart of the above characterization

References

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