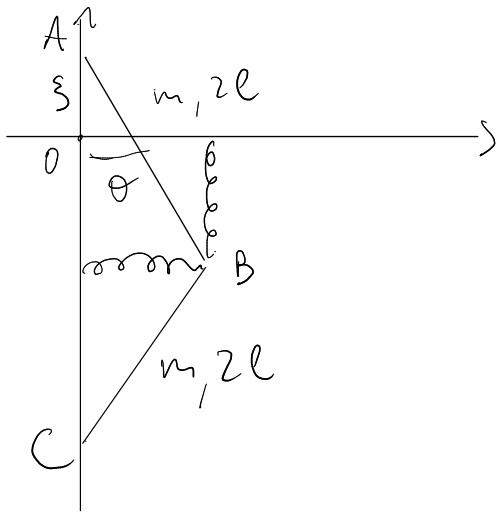


18/7/25



$$(G_1 - O) = (G_1 - A) + (A - O)$$

$$= l \sin \theta, \xi - l \cos \theta$$

$$(B - O) = (B - A) + (A - O)$$

$$= 2l \sin \theta, \xi - 2l \cos \theta$$

$$(G_2 - O) = (G_2 - B) + (B - O)$$

$$= l \sin \theta, \xi - 3l \cos \theta$$

$$U = -mg(y_{G_1} + y_{G_2}) - \frac{1}{2} k |B - O|^2$$

$$= -mg(2\xi - 4l \cos \theta) - \frac{1}{2} k (\xi^2 - 4l\xi \cos \theta) + \text{const}$$

$$= -2mg\xi + 4mgl \cos \theta - \frac{1}{2} k \xi^2 + 2kl\xi \cos \theta + c$$

$$\frac{\partial U}{\partial \xi} = -2mg - k\xi + 2kl \cos \theta = 0$$

$$\frac{\partial U}{\partial \theta} = -4mgl \sin \theta - 2kl\xi \sin \theta = 0$$

$$2l \sin \theta (2mg + k\xi) = 0$$

$$\theta = 0 \quad -2mg - k\xi + 2kl = 0$$

$$\xi = 2l - \frac{2mg}{k} = 2l(1 - \lambda)$$

$$\theta = \pi \quad -2mg - k\xi - 2kl = 0$$

$$\xi = -2l - \frac{2mg}{k} = -2l(1 + \lambda)$$

$$P_1(2l(1 - \lambda), 0) \quad P_2(-2l(1 + \lambda), \pi)$$

$$2mg + k\zeta = 0 \quad \zeta = -\frac{2mg}{k} = -2\lambda l$$

$$-\cancel{2mg} + \cancel{2mg} + 2kl \cos \theta = 0$$

$$\cos \theta = 0 \quad \theta = \frac{\pi}{2}, \frac{3}{2}\pi$$

$$P_3 = (-2\lambda l, \frac{\pi}{2}) \quad P_4 = (-2\lambda l, \frac{3}{2}\pi)$$

$$H = \begin{bmatrix} -k & -2kl \sin \theta \\ -2kl \sin \theta & -4mgl \cos \theta - 2kl\zeta \cos \theta \end{bmatrix}$$

$$H(P_1) = \begin{bmatrix} -k & 0 \\ 0 & -4mgl - 4kl^2(1-\lambda) \\ & -4kl^2(\cancel{\lambda} + 1 - \cancel{\lambda}) \\ & -4kl^2 < 0 \end{bmatrix}$$

STAB.

$$H(P_2) = \begin{bmatrix} -k & 0 \\ 0 & +4mgl - 4kl^2(1+\lambda) \\ & 4kl^2(\cancel{\lambda} - 1 - \cancel{\lambda}) < 0 \end{bmatrix}$$

STAB.

$$H(P_{3,4}) = \begin{bmatrix} -k & \mp 2kl \\ \mp 2kl & 0 \end{bmatrix} \quad \text{IN ST.}$$

$$V_{G_1} = l \dot{\theta} \cos \theta, \quad \dot{\xi} + l \dot{\theta} \sin \theta$$

$$V_{G_2} = l \dot{\theta} \cos \theta, \quad \dot{\xi} + 3l \dot{\theta} \sin \theta$$

$$|V_{G_1}|^2 = l^2 \dot{\theta}^2 + \dot{\xi}^2 + 2l \dot{\xi} \dot{\theta} \sin \theta$$

$$|V_{G_2}|^2 = \dot{\xi}^2 + l^2 \dot{\theta}^2 (\underbrace{\cos^2 \theta + 9 \sin^2 \theta}_{1 + 8 \sin^2 \theta}) + 6l \dot{\xi} \dot{\theta} \sin \theta$$

$$K = \frac{1}{2} m \left(2 \dot{\xi}^2 + l^2 \dot{\theta}^2 (2 + 8 \sin^2 \theta) + 8l \dot{\xi} \dot{\theta} \sin \theta \right) + \frac{1}{2} \frac{2}{3} m l^2 \dot{\theta}^2$$

$$= \frac{1}{2} m \left(2 \dot{\xi}^2 + \left(\frac{8}{3} + 8 \sin^2 \theta \right) l^2 \dot{\theta}^2 + 8l \dot{\xi} \dot{\theta} \sin \theta \right)$$

$$K = \begin{bmatrix} 2m & 4ml \sin \theta \\ 4ml \sin \theta & \left(\frac{8}{3} + 8 \sin^2 \theta \right) m l^2 \end{bmatrix}$$

$$K(P_1) = \begin{bmatrix} 2m & 0 \\ 0 & \frac{8}{3} m l^2 \end{bmatrix} \quad H(P_1) = \begin{bmatrix} -k & 0 \\ 0 & -4kl^2 \end{bmatrix}$$

$$\tilde{L} = \frac{1}{2} \left(2m \dot{\xi}^2 + \frac{8}{3} m l^2 \dot{\theta}^2 \right) + \frac{1}{2} \left[k (\xi - 2l(1-\lambda))^2 + 4kl^2 \theta^2 \right]$$

□

II) Lanza quadrata $\begin{bmatrix} \frac{m l^2}{3} & \frac{m l^2}{3} & \frac{2}{3} m l^2 \end{bmatrix}$

$$d = (l\sqrt{2}, l\sqrt{2}, 0) \quad d^2 = 4l^2$$

$$d^2 I - d \otimes d = \begin{bmatrix} 2l^2 & -2l^2 & 0 \\ -2l^2 & 2l^2 & 0 \\ 0 & 0 & 4l^2 \end{bmatrix}$$

$$J_Q = \begin{bmatrix} \frac{7}{3} m l^2 & -2 m l^2 & 0 \\ -2 m l^2 & \frac{7}{3} m l^2 & 0 \\ 0 & 0 & \frac{14}{3} m l^2 \end{bmatrix}$$

$$J_{\text{astr}} = \begin{bmatrix} \frac{m l^2}{6} & -\frac{m l^2}{6} & 0 \\ -\frac{m l^2}{6} & \frac{m l^2}{6} & 0 \\ 0 & 0 & \frac{m l^2}{3} \end{bmatrix}$$

$$J_{\text{tot}} = \begin{bmatrix} \frac{29}{6} m l^2 & -\frac{25}{6} m l^2 & 0 \\ -\frac{25}{6} m l^2 & \frac{29}{6} m l^2 & 0 \\ 0 & 0 & \frac{29}{3} m l^2 \end{bmatrix}$$

