

Non-linear Wave Propagation and Non-Equilibrium Thermodynamics - Part 3

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The Physical laws in continuum theories are *balance laws*: Let $\mathbf{F}^0(\mathbf{x}, t)$; $\mathbf{x} \in \Omega$, $t \in R^+$, a generic density. The time derivative in the domain Ω is expressed by

$$\frac{d}{dt} \int_{\Omega} \mathbf{F}^0 d\Omega = - \int_{\Sigma} \mathbf{G}^i n_i d\Sigma + \int_{\Omega} \mathbf{f} d\Omega, \quad (1)$$

where the first integral on the r.h.s. represents the flux of some quantities \mathbf{G}^i through the surface Σ of unit normal \vec{n} and velocity \vec{v} , while the last integral represents the productions.

Under regularity assumptions the system can be put in the local form:

$$\frac{\partial \mathbf{F}^0}{\partial t} + \frac{\partial \mathbf{F}^i}{\partial x^i} = \mathbf{f}, \quad \mathbf{F}^i = \mathbf{F}^0 v^i + \mathbf{G}^i \quad (2)$$

For example in the case of fluids:

$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho v_i}{\partial x^i} = 0 \quad (\text{mass balance})$$

$$\frac{\partial(\rho v_j)}{\partial t} + \frac{\partial}{\partial x^i}(\rho v_i v_j - t_{ij}) = 0 \quad (\text{balance of momentum}) \quad (3)$$

$$\frac{\partial E}{\partial t} + \frac{\partial}{\partial x^i}(E v_i + q_i - t_{ij} v_j) = 0 \quad (\text{energy conservation}).$$

where $E = \rho \frac{v^2}{2} + \rho \varepsilon$ and $\rho, \mathbf{v} \equiv (v_i), \mathbf{t} \equiv (t_{ij}), \mathbf{q} \equiv (q_i), \varepsilon$ are the density, the velocity, the stress tensor, the heat flux and the internal energy.

Of course the system is not closed and we need the so called *constitutive equations*.

In the modern constitutive theory all the constitutive equations must obey the two principles:

- The objectivity principle: the proper constitutive equations are independent of the Observer;
- The second principle of thermodynamics that in the Rational Thermodynamics requires that any solutions of the full system satisfies the inequality of Clausius-Duhem (Coleman-Noll 1963):

$$\frac{\partial \rho S}{\partial t} + \frac{\partial}{\partial x^i} \left(\rho S v^i + \frac{q^i}{T} \right) \geq 0 \quad \text{for all processes} \quad (4)$$

For instance in the case of classical approach of fluids with Fourier Navier-Stokes assumptions

$$\mathbf{t} = -p\mathbf{l} + \boldsymbol{\sigma}$$
$$q^i = -\chi \frac{\partial T}{\partial x^i}; \quad \sigma_{\langle ij \rangle} = \mu \frac{\partial v_{\langle i}}{\partial x^{j \rangle}}; \quad \sigma_{||} = \nu \operatorname{div} \mathbf{v},$$

the constitutive equations compatible with (4) require the existence of a *free energy* ψ , function of the density ρ and temperature T , such that:

$$p = \rho^2 \frac{\partial \psi}{\partial \rho}, \quad S = -\frac{\partial \psi}{\partial T}, \quad \varepsilon = \psi - T \frac{\partial \psi}{\partial T}, \quad (5)$$

while

$$\chi \text{ (heat conductivity), } \mu \text{ (shear viscosity), } \nu \text{ (bulk viscosity)} \geq 0.$$

The entropy principle is also supported by the kinetic theory of gases. In fact from the Boltzmann equation

$$\frac{\partial f}{\partial t} + c^i \frac{\partial f}{\partial x^i} = Q; \quad f \equiv f(\mathbf{x}, t, \mathbf{c})$$

introducing as moment:

$$\rho S = \int (-k \log f) f \, d\mathbf{c}; \quad \phi^i = \int (-k \log f) f c^i \, d\mathbf{c};$$

we have the so called H-theorem:

$$\frac{\partial \rho S}{\partial t} + \frac{\partial}{\partial x^i} (\rho S v^i + \phi^i) \geq 0 \quad (6)$$

but the non convective entropy flux ϕ^i is in general different from q^i/T .

The necessity to extend the entropy principle with a general entropy flux was proposed by INGO MÜLLER (1967).

At present the general form (6)

$$\frac{\partial \rho S}{\partial t} + \frac{\partial}{\partial x^i} (\rho S v^i + \phi^i) \geq 0$$

is universally accepted in the continuum community and all the constitutive equations in new models are tested by the entropy principle.

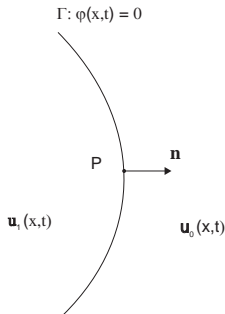
For systems (2) we can define the so called *weak solution*:

$$\int_V (\mathbf{u} \partial_t \Phi + \mathbf{F}^i \partial_i \Phi) dV = 0 \quad (7)$$

for any test function Φ .

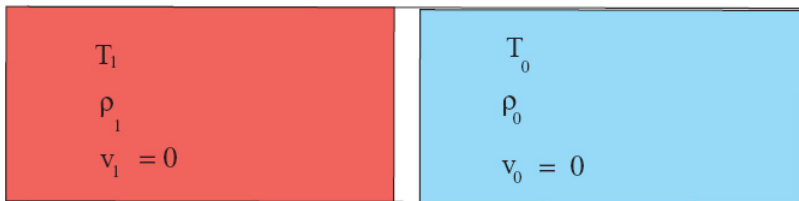
In a particular a shock wave is a weak solution of (2) iff across the shock front the Rankine-Hugoniot equations are fulfilled:

$$-s [\mathbf{u}] + [\mathbf{F}^i] n_i = 0.$$





The Riemann problem was originated by the following well know problem in fluidynamics:



The Riemann Problem

Let us consider quasi-linear system of conservation laws compatible with an entropy principle with a convex entropy density:

$$\partial_t \mathbf{u} + \partial_x \mathbf{F}(\mathbf{u}) = 0$$

$$\partial_t h(\mathbf{u}) + \partial_x k(\mathbf{u}) \leq 0.$$

with initial data

$$\mathbf{u}(x, 0) = \begin{cases} \mathbf{u}_0 & \text{for } x > 0 \\ \mathbf{u}_1 & \text{for } x < 0. \end{cases}$$

The Riemann Problem and the non uniqueness of weak solutions

Before we recall how the Riemann Problem was solved we remember a peculiarity of the weak solutions: *the non uniqueness!*

To explain this let's consider the Burger equation

$$u_t + \left(\frac{u^2}{2} \right)_x = 0$$

equivalent to

$$u_t + uu_x = 0$$

with initial data

$$u(x, 0) = \begin{cases} u_0 & \text{for } x > 0 \\ u_1 & \text{for } x < 0 \end{cases}$$

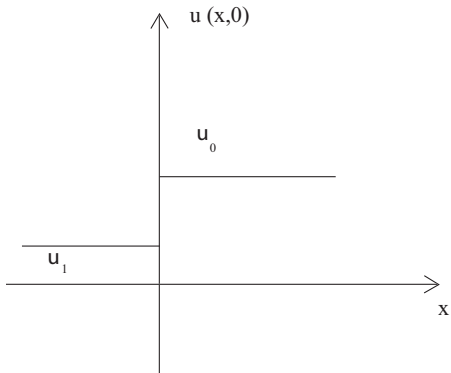


Figure: Initial data

If we are looking for a shock solution, along the curve $dx/dt = s$ the R-H condition must be satisfied. In this case this turns into:

$$-s[u] + [u^2/2] = 0 \quad (9)$$

and we can get the velocity of the shock, s

$$s = \frac{[u^2/2]}{[u]} = \frac{1}{2}(u_0 + u_1). \quad (10)$$

So we have the weak solution

$$u(x, t) = \begin{cases} u_0 & \text{per } x > st \\ u_1 & \text{per } x < st \end{cases} ; \quad \text{with } s = \frac{1}{2}(u_0 + u_1). \quad (11)$$

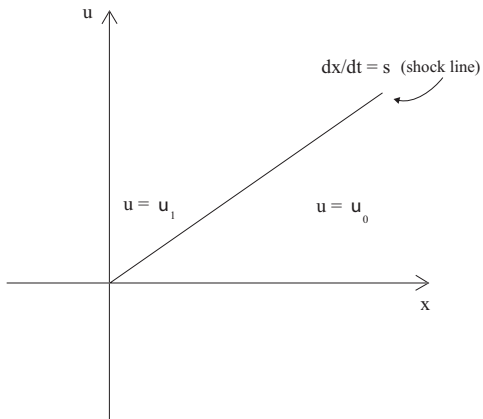


Figure: Shock wave

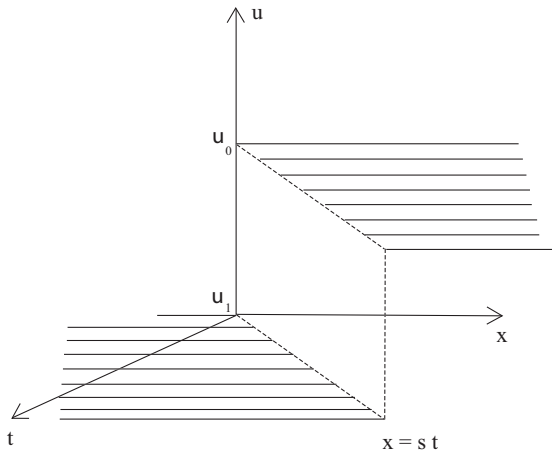
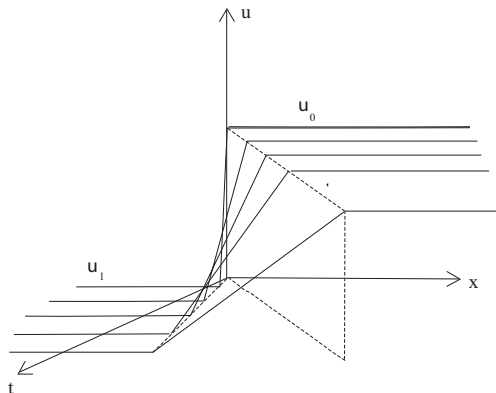


Figure: Shock wave in space-time

We can see that we have also the following solution $u(x, t)$

$$u(x, t) = \begin{cases} u_1 & \text{per } \frac{x}{t} < u_1 \\ \frac{x}{t} & \text{per } u_1 \leq \frac{x}{t} \leq u_0 \\ u_0 & \text{per } \frac{x}{t} > u_0 \end{cases} \quad (12)$$



The solution (12)

- is compatible with the initial data;
- is continuous for any $t > 0$;
- is differentiable;
- is a weak solution

So we have found **two different solutions** of this Riemann problem. Both of them are acceptable from a mathematical point of view, but from a physical point of view only one of them should be acceptable.

Which is the physically acceptable solution?

In the present case the characteristic velocity $\lambda = u$ and the characteristic curves are straight lines represented by the equations $x = u_0 t + x_0$ and $x = u_1 t + x_0$.

- If $\lambda(u_1) < \lambda(u_0)$ the two families of characteristics **do not** intersect for any $t > 0$;
- If $\lambda(u_1) > \lambda(u_0)$ the two families of characteristics **do** intersect for $t > 0$.

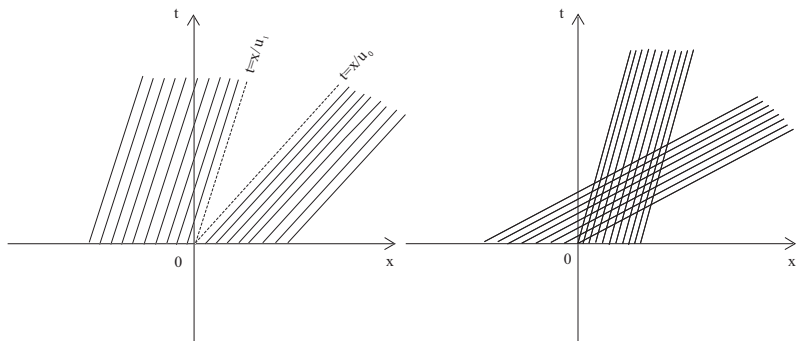


Figure: Non-intersecting and intersecting characteristic lines

The **Lax condition** select the admissible shock:

$$\lambda(u_0) < s < \lambda(u_1). \quad (13)$$

The entropy growth:

$$u_t + \left(\frac{u^2}{2}\right)_x = 0, \quad -s[u] + \left[\frac{u^2}{2}\right] = 0, \quad u_1 = 2s - u_0;$$

$$\left(\frac{u^2}{2}\right)_t + \left(\frac{u^3}{3}\right)_x = 0, \quad \eta = -s \left[\frac{u^2}{2}\right] + \left[\frac{u^3}{3}\right];$$

$$\eta = \frac{2}{3}(s - \lambda_0)^3 > 0 \quad \rightarrow \quad s > \lambda_0$$

and as

$$s = (\lambda_1 + \lambda_0)/2 \quad \rightarrow \quad s < \lambda_1$$

i.e. the equivalence between the Lax condition and the entropy growth condition:

$$\lambda(u_0) < s < \lambda(u_1) \Leftrightarrow \eta > 0. \quad (14)$$

Both are also justified by the artificial viscosity method:

$$u_t + uu_x = \nu u_{xx} \quad (15)$$

taking the limit of $\nu \rightarrow 0$.

The general Lax solution:



Let

$$\mathbf{A} = \nabla \mathbf{F}; \quad (\mathbf{A} - \lambda \mathbf{I})\mathbf{r} = 0.$$

The Riemann problem for initial sufficiently small jump is solved as a "superposition" of shocks, characteristic shocks, rarefaction waves and constant states. The physical shocks are those for which:

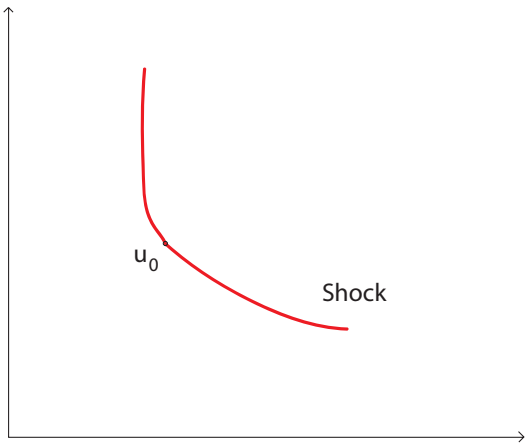
Shock:

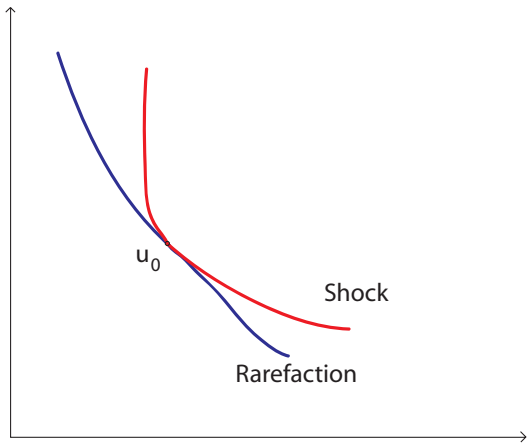
$$\text{if } \nabla \lambda \cdot \mathbf{r} \neq 0, \quad \lambda(\mathbf{u}_0) < s < \lambda(\mathbf{u}_1) \iff \eta > 0$$

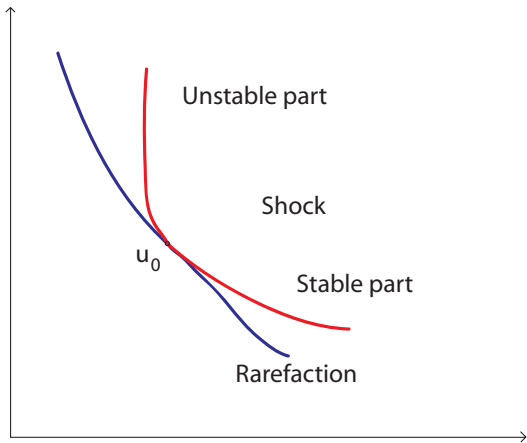
Characteristic Shock:

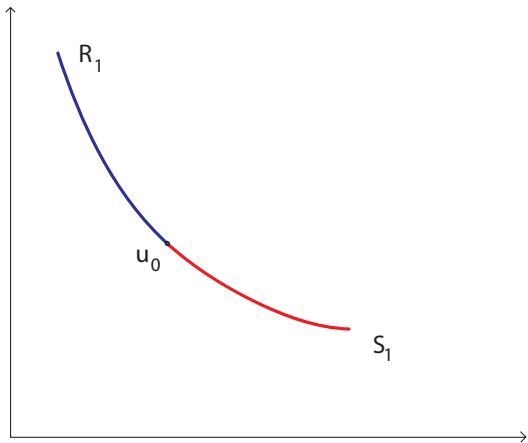
$$\text{if } \nabla \lambda \cdot \mathbf{r} \equiv 0, \quad \lambda(\mathbf{u}_0) = s = \lambda(\mathbf{u}_1) \iff \eta = 0$$

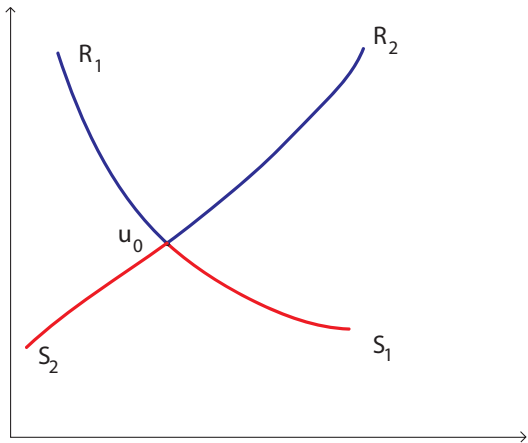
while if $\lambda(\mathbf{u}_1) < \lambda(\mathbf{u}_0)$ we have a rarefaction wave.











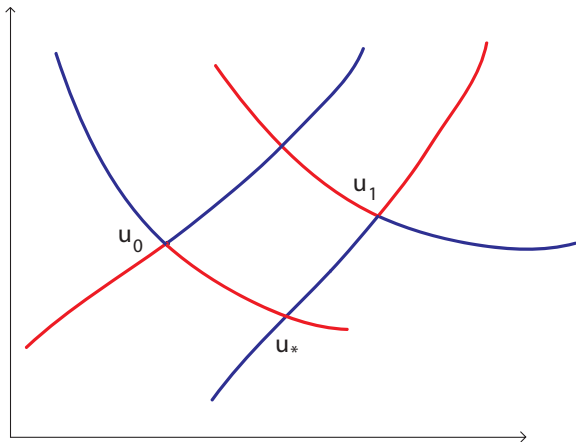




Figure: The Euler solution for the density - $t = 0$

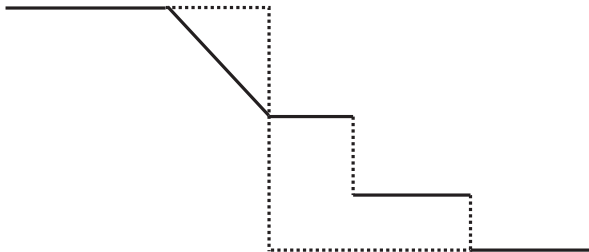
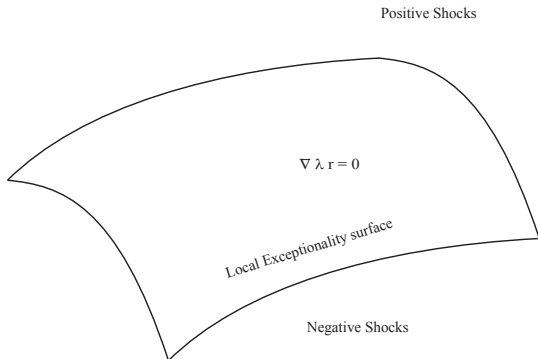


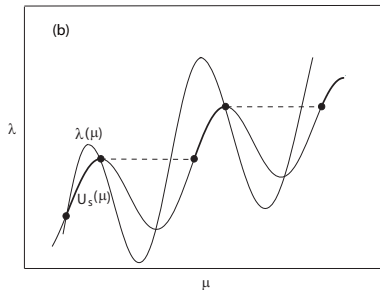
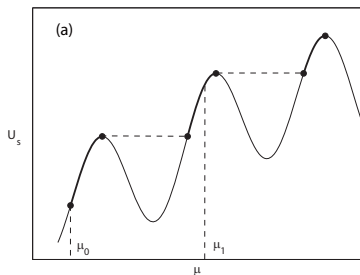
Figure: The Euler solution for the density - $t > 0$

The problem fails in the special case of local exceptionality

$$\nabla \lambda \cdot \mathbf{r} = 0 \quad \text{for some } \mathbf{u}.$$



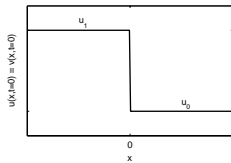
In this case the stability of the shock must satisfy the Liu conditions that implies the generalized Lax condition $\lambda(\mathbf{u}_0) \leq s \leq \lambda(\mathbf{u}_1)$ but the entropy growth is not sufficient; it is necessary to add additional conditions for example a new superposition principle (LIU, RUGGERI, 2003).



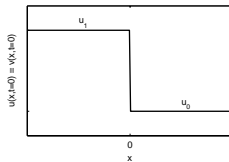
The Riemann problem is a fundamental tool for the existence theorem for solutions of the initial data (Glimm, Dafermos, Bressan, Bianchini,...) as well for numerically approach (Godunov, Russo,.....).

See the book of C. Dafermos, *Hyperbolic Conservation Laws in Continuum Physics*. Springer Verlag, Berlin.

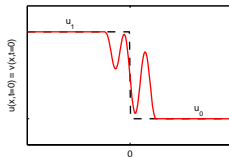
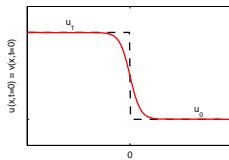
- Riemann (R) problem



- Riemann (R) problem



- Riemann with Structure (RS) problem



The importance of the Riemann Problem is evident also for the following asymptotic results due to Tai-Ping Liu:

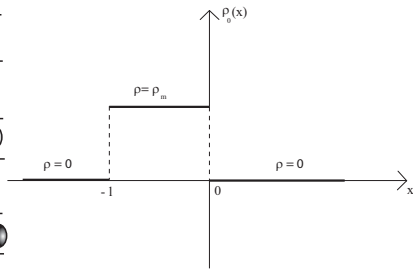
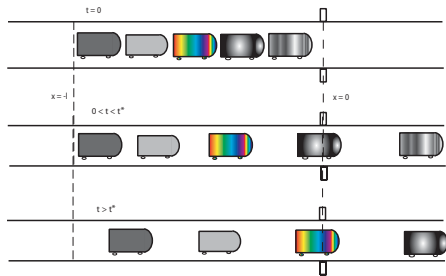
Theorem

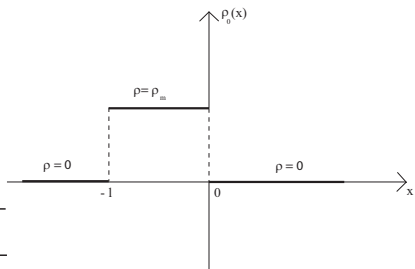
If the initial data are "perturbations" of the Riemann data, i.e. at $x = \pm\infty$ there are two constant states then for t large the solutions tends to the one of the Riemann problem for genuine non-linear characteristic, while waves of linearly degenerate characteristic velocities tend to traveling waves.

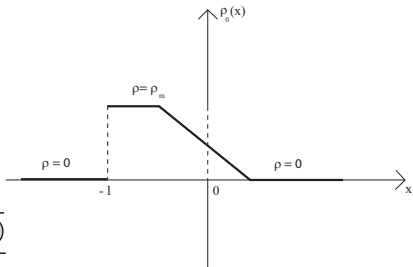
In particular if the initial data are perturbations of a constant state then for t large the solutions converge to the constant state.

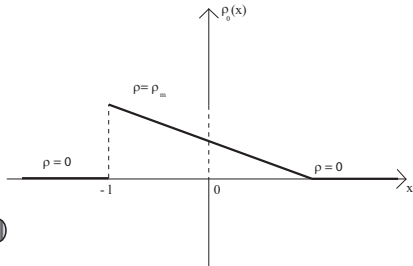
Example of the traffic problem:

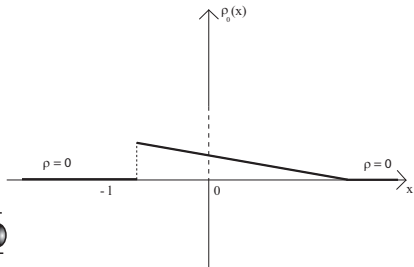
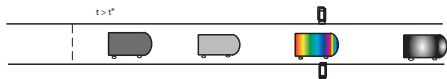
$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho v}{\partial x} = 0 \quad v(\rho) = v_m \left(1 - \frac{\rho}{\rho_m} \right).$$











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