

Contents lists available at SciVerse ScienceDirect

Journal of Mathematical Analysis and Applications

journal homepage: www.elsevier.com/locate/jmaa

Symmetry of *n*-mode positive solutions for two-dimensional Hénon type systems



CrossMark

Naoki Shioji^a, Marco Squassina^{b,*}

^a Department of Mathematics, Faculty of Engineering, Yokohama National University, Tokiwadai, Hodogaya-ku, Yokohama 240-8501, Japan

^b Dipartimento di Informatica, Università degli Studi di Verona, Cá Vignal 2, Strada Le Grazie 15, 37134 Verona, Italy

ARTICLE INFO

Article history: Received 30 January 2013 Available online 27 March 2013 Submitted by V. Radulescu

Keywords: Radial symmetry Hénon type systems *n*-mode positive solutions

1. Introduction and results

Let $D = \{x \in \mathbb{R}^2 : |x| < 1\}$ and, for $m \in \mathbb{N}$ with $m \ge 2$, consider the system

$$\begin{cases} \Delta u^i + f^i(|\mathbf{x}|, u^i) = 0 & \text{in } D, \\ u^i = 0 & \text{on } \partial D, \end{cases} \quad \text{for } i = 1, \dots, m, \tag{1.1}$$

where f^i are smooth functions over $(0, 1) \times (0, \infty)^m$. Semi-linear elliptic systems as (1.1) arise naturally in many physical and biological contests; see e.g. [8,15,16,18,20] and the references therein. As far as the symmetry of positive solutions is concerned and the functions f^i are decreasing in the radial variable, the celebrated moving plane method [9] can be applied when the system is cooperative namely $\partial f^i/\partial u^i \ge 0$ for every $i \ne j$ [6,13,21]. The aim of this note is to establish a general symmetry result (Theorem 1.1) for *n*-mode $(2\pi/n$ -rotation invariant) solutions, namely solutions (u^1, \ldots, u^m) such that each component $u^i : \overline{D} \to \mathbb{R}$, in polar coordinates, satisfies

 $u^{i}(r, \theta) = u^{i}(r, \theta + 2\pi/n), \text{ for all } (r, \theta) \in [0, 1] \times \mathbb{R},$

as well as provide a meaningful application of it (Theorem 1.2) to the system of Hénon type

$$\begin{cases} \Delta u + \frac{2p}{p+q} |x|^{\alpha} u^{p-1} v^{q} = 0 & \text{in } D, \\ \Delta v + \frac{2q}{p+q} |x|^{\alpha} u^{p} v^{q-1} = 0 & \text{in } D, \\ u > 0, \quad v > 0 & \text{in } D, \\ u = v = 0 & \text{on } \partial D. \end{cases}$$
(1.2)

* Corresponding author.

ABSTRACT

We provide a symmetry result for *n*-mode positive solutions of a general class of semilinear elliptic systems under cooperative conditions on the nonlinearities. Moreover, we apply the result to a class of Hénon systems and provide the existence of multiple *n*-mode positive solutions.

© 2013 Elsevier Inc. All rights reserved.

E-mail addresses: shioji@ynu.ac.jp (N. Shioji), marco.squassina@univr.it (M. Squassina).

⁰⁰²²⁻²⁴⁷X/\$ - see front matter © 2013 Elsevier Inc. All rights reserved. http://dx.doi.org/10.1016/j.jmaa.2013.03.056

Quite recently, these systems were carefully investigated in [22,23] (see also [1,10,11] and references therein) and they can be considered as a vectorial counterpart of the celebrated equation

$$\begin{cases} \Delta u + |x|^{\alpha} u^{p-1} = 0 & \text{in } D, \\ u > 0 & \text{in } D, \\ u = 0 & \text{on } \partial D, \end{cases}$$

first studied in [17] after being introduced by Hénon in [12] in connection with the research of rotating stellar structures. We shall say that u is of class C^n at the origin if u is of class C^{n-1} in a neighborhood of the origin and each (n - 1)-th partial derivative is totally differentiable at the origin. Then we prove the following

Theorem 1.1. Let $m, n \in \mathbb{N}$ with $m, n \geq 2$ and $f^1, \ldots, f^m \in C((0, 1) \times (0, \infty)^m, \mathbb{R})$ such that

(i) for each $i \in \{1, ..., m\}$ and $(u^1, ..., u^m) \in (0, \infty)^m$, the map

$$r \mapsto r^{2-2n} f^i(r, u^1, \dots, u^m) : (0, 1) \to \mathbb{R}$$

is nonincreasing;

(ii) for each $i \in \{1, ..., m\}$ and $r \in (0, 1), f^{i}(r, \cdot, ..., \cdot) \in C^{1}((0, \infty)^{m}, \mathbb{R});$

(iii) for each $i, j \in \{1, ..., m\}$ with $i \neq j$ and $(r, u^1, ..., u^m) \in (0, 1) \times (0, \infty)^m$,

$$\frac{\partial f^i}{\partial u^j}(r, u^1, \ldots, u^m) \ge 0;$$

(iv) for each $i, j \in \{1, ..., m\}, r_0 \in (0, 1)$ and $M \in (0, \infty)$,

$$\sup\left\{\left|\frac{\partial f^i}{\partial u^j}(r, u^1, \ldots, u^m)\right| : (r, u^1, \ldots, u^m) \in (r_0, 1) \times (0, M]^m\right\} < \infty.$$

Let $(u^1, \ldots, u^m) \in C^2(D \setminus \{0\}) \cap C(\overline{D})$ be a solution of (1.1) such that each u^i is n-mode, positive and of class C^n at the origin. Then, each u^i is radially symmetric and $\frac{\partial u^i}{\partial r}(|\mathbf{x}|) < 0$ for $r = |\mathbf{x}|$.

For scalar equations, this result was obtained in [19]. Due to the recent interest of the community for the symmetry issues for elliptic systems, we believe that the statement above is of interest. Also, it admits some interesting consequences; see for instance Theorem 1.2 below. Of course, system (1.1) includes both variational and nonvariational problems or systems of Hamiltonian type; see e.g. [7] for a wide overview. We point out, in particular, that the weakly coupled semi-linear Schrödinger systems, see [14] and the references therein, which come from physically relevant situations and have recently received much attention, satisfy conditions (ii)–(iv).

For the sake of completeness, we refer the reader to [3–5] for recent partial (foliated Schwarz symmetry) symmetry results for the smooth solutions to (1.1) in rotationally invariant domains and for possibly sign-changing solutions and where the maps $r \mapsto f^i(r, s_1, \ldots, s^m)$ are possibly nondecreasing and some convexity assumptions are assumed on the s_i variables.

For every $\alpha \ge 0$ and p, q > 1, let us set

$$R_{\alpha,p,q}(u,v) := \frac{\int_{D} (|\nabla u|^{2} + |\nabla v|^{2})}{\left(\int_{D} |x|^{\alpha} |u|^{p} |v|^{q}\right)^{\frac{2}{p+q}}}, \quad \text{for any } u, v \in H_{0}^{1}(D).$$

Moreover, for each $\gamma > 0$, we shall denote by $\lceil \gamma \rceil$ the smallest integer greater than or equal to γ . Then, we have the following

Theorem 1.2. The following facts hold.

- (I) If $\alpha \in (0, \infty)$, $p, q \in (1, \infty)$ and (u, v) is an n-mode solution of (1.2) with $n \ge 1 + \lceil \alpha/2 \rceil$, then u, v are radially symmetric.
- (III) For each $\alpha \in (2, \infty)$ and $p, q \in (1, \infty)$, if $n_{\alpha} \ge 1$ then (1.2) has a nonradial n-mode solution (u_n, v_n) for $n = 1, \ldots, n_{\alpha}$ such that

$$R_{\alpha,p,q}(u_1,v_1) < \dots < R_{\alpha,p,q}(u_{n_\alpha},v_{n_\alpha}), \tag{1.3}$$

where n_{α} is the greatest integer less than

$$\left(\frac{\alpha+2}{2\alpha}\right)^{\overline{p+q-2}} \left(\frac{\alpha-2}{\alpha}\right)^{\frac{\alpha}{p+q-2}} \left(1+\frac{\alpha}{2}\right).$$
(1.4)

In particular, the following facts hold.

- (i) For each $\alpha \in (2, \infty)$, if at least one of $p, q \in (1, \infty)$ is large enough, then $n_{\alpha} = \lceil \alpha/2 \rceil$, that is (1.2) has a nonradial *n*-mode solution for $n = 1, ..., \lceil \alpha/2 \rceil$ satisfying (1.3).
- (ii) For each $p, q \in (1, \infty)$ and $\ell \in \mathbb{N}$, if $\alpha \in (2, \infty)$ is large enough (1.2) has a nonradial n-mode solution (u_n, v_n) for $n = 1, \ldots, \ell$ such that

 $R_{\alpha,p,q}(u_1, v_1) < \cdots < R_{\alpha,p,q}(u_\ell, v_\ell).$ In particular, for each $p, q \in (1, \infty)$, the number of nonradial solutions of (1.2) tends to infinity as $\alpha \to \infty$.

Hence, as far as α gets large, the symmetry breaking phenomenon occurs and we can find as many *n*-mode positive solutions as we want. In Section 2 we shall prove Theorem 1.1, while in Section 3 we shall provide the proof of Theorem 1.2.

2. Proof of Theorem 1.1

By using the planar polar coordinates, for each i = 1, ..., m, we define the function $\tilde{u}^i : \overline{D} \to \mathbb{R}$ by setting $\tilde{u}^i(r, \theta) := u^i(r^{1/n}, \theta/n)$, for every $(r, \theta) \in \overline{D}$. Since $(u^1, ..., u^m)$ satisfies system (1.1) and each u^i is *n*-mode, we can see that $\tilde{u}^i \in C^2(D \setminus \{0\}) \cap C(\overline{D})$ and $(\tilde{u}^1, ..., \tilde{u}^m)$ satisfies the system

$$\begin{cases} \Delta \widetilde{u}^{i} + \widetilde{f}^{i}(|x|, \widetilde{u}^{1}, \dots, \widetilde{u}^{m}) = 0 & \text{in } D \setminus \{0\}, \\ \widetilde{u}^{i} = 0 & \text{on } \partial D, \end{cases} \quad \text{for } i = 1, \dots, m.$$

$$(2.1)$$

Here, $\tilde{f}^i \in C((0, 1) \times (0, \infty)^m, \mathbb{R})$ is the function defined by

$$\widetilde{f}^{i}(r, t^{1}, \ldots, t^{m}) := n^{-2} r^{(2-2n)/n} f^{i}(r^{1/n}, t^{1}, \ldots, t^{m}),$$

for every $(r, t^1, ..., t^m) \in (0, 1) \times (0, \infty)^m$ and \tilde{f}^i satisfies

for each
$$(t^1, \dots, t^m) \in (0, \infty)^m, r \mapsto \tilde{f}^i(r, t^1, \dots, t^m)$$
 is nonincreasing. (2.2)

Indeed, from

$$\begin{split} \Delta \widetilde{u}^{i}(r,\theta) + \widetilde{f}^{i}(r,\widetilde{u}^{1}(r,\theta),\ldots,\widetilde{u}^{m}(r,\theta)) &= \frac{1}{n^{2}} r^{\frac{2-2n}{n}} \left(u_{rr}^{i}\left(r^{\frac{1}{n}},\frac{\theta}{n}\right) + \frac{1}{r^{\frac{1}{n}}} u_{r}^{i}\left(r^{\frac{1}{n}},\frac{\theta}{n}\right) + \frac{1}{r^{\frac{2}{n}}} u_{\theta\theta}^{i}\left(r^{\frac{1}{n}},\frac{\theta}{n}\right) \right. \\ &\left. + f^{i}\left(r^{\frac{1}{n}},u^{1}\left(r^{\frac{1}{n}},\frac{\theta}{n}\right),\ldots,u^{m}\left(r^{\frac{1}{n}},\frac{\theta}{n}\right)\right) \right) = 0, \end{split}$$

we deduce (2.1), and we can easily see that (2.2) holds as well, in light of assumption (i). For each $\lambda \in (0, 1)$, we set $\Sigma_{\lambda} = \{x \in D : x_1 > \lambda\}$ and we define the map $h_{\lambda} : \overline{\Sigma_{\lambda}} \to \overline{D}$ by $h_{\lambda}(x) = (2\lambda - x_1, x_2)$ for $x = (x_1, x_2) \in \overline{\Sigma_{\lambda}}$. We note that h_{λ} satisfies

$$|h_{\lambda}(x)| < |x| \text{ for each } \lambda \in (0, 1) \text{ and } x \in \Sigma_{\lambda} \cup \operatorname{Int}_{\partial D}(\overline{\Sigma_{\lambda}} \cap \partial D).$$
 (2.3)

Here, for a subset *E* of ∂D , we denote by $Int_{\partial D}E$, the interior set of *E* with respect to the relative topology of ∂D . We set $x_{\lambda} = (2\lambda, 0)$ for $\lambda \in (0, 1)$. We can see

$$x_{\lambda} \in \begin{cases} \Sigma_{\lambda} & \text{ for each } \lambda \in \left(0, \frac{1}{2}\right), \\ \partial \Sigma_{\lambda} & \text{ for } \lambda = \frac{1}{2}, \\ \mathbb{R}^{2} \setminus \overline{\Sigma_{\lambda}} & \text{ for each } \lambda \in \left(\frac{1}{2}, 1\right) \end{cases}$$

$$(2.4)$$

and

$$h_{\lambda}(x_{\lambda}) = 0 \quad \text{for each } \lambda \in (0, 1/2].$$
(2.5)

For the sake of completeness, we note that $\Sigma_{\lambda} \setminus \{x_{\lambda}\} = \Sigma_{\lambda}$ for each $\lambda \in [\frac{1}{2}, 1)$ and $\overline{\Sigma_{\lambda}} \setminus \{x_{\lambda}\} = \overline{\Sigma_{\lambda}}$ for each $\lambda \in (\frac{1}{2}, 1)$. For each i, j = 1, ..., m, we define $v_{\lambda}^{i} \in C^{2}(\Sigma_{\lambda} \setminus \{x_{\lambda}\}) \cap C(\overline{\Sigma_{\lambda}})$ and $c_{\lambda}^{ij} \in L^{\infty}(\Sigma_{\lambda})$ by setting

$$v_{\lambda}^{i}(x) := \widetilde{u}^{i}(x) - \widetilde{u}^{i}(h_{\lambda}(x)), \quad \text{for } x \in \overline{\Sigma_{\lambda}},$$
(2.6)

and

$$c_{\lambda}^{ij}(x) := -\int_{0}^{1} \frac{\partial \widetilde{f}^{i}}{\partial u^{i}} \left(|x|, s\widetilde{u}^{1}(x) + (1-s)\widetilde{u}^{1}(h_{\lambda}(x)), \dots, s\widetilde{u}^{m}(x) + (1-s)\widetilde{u}^{m}(h_{\lambda}(x)) \right) ds.$$

$$(2.7)$$

By the assumptions of Theorem 1.1, we can see that $c_{\lambda}^{ij} \leq 0$ if $i \neq j$ for $x \in \Sigma_{\lambda}$ and

$$\sup_{r<\lambda<1}\sup_{x\in\Sigma_{\lambda}}\sup_{x\in\Sigma_{\lambda}}|c_{\lambda}^{ij}(x)|<\infty,\quad\text{for each }r\in(0,1)\text{ and }i,j=1,\ldots,m.$$
(2.8)

Therefore, it holds

$$-\Delta v_{\lambda}^{i}(x) + \sum_{j=1}^{m} c_{\lambda}^{ij}(x) v_{\lambda}^{j}(x) \leq 0 \quad \text{for } \lambda \in (0, 1), x \in \Sigma_{\lambda} \setminus \{x_{\lambda}\} \text{ and } i = 1, \dots, m.$$

$$(2.9)$$

Indeed, (2.9) can be obtained as follows:

$$0 = \Delta \widetilde{u}^{i}(h_{\lambda}(x)) + \widetilde{f}^{i}(|h_{\lambda}(x)|, \widetilde{u}^{1}(h_{\lambda}(x)), \dots, \widetilde{u}^{m}(h_{\lambda}(x))) - \Delta \widetilde{u}^{i}(x) - \widetilde{f}^{i}(|x|, \widetilde{u}^{1}(x), \dots, \widetilde{u}^{m}(x))$$

$$\geq -\Delta v_{\lambda}^{i}(x) + \widetilde{f}^{i}(|x|, \widetilde{u}^{1}(h_{\lambda}(x)), \dots, \widetilde{u}^{m}(h_{\lambda}(x))) - \widetilde{f}^{i}(|x|, \widetilde{u}^{1}(x), \dots, \widetilde{u}^{m}(x))$$

$$= -\Delta v_{\lambda}^{i}(x) + \sum_{j=1}^{m} c_{\lambda}^{ij}(x) v_{\lambda}^{j}(x).$$

We set

$$A_1 = \{\lambda \in [1/2, 1) : v_{\lambda}^i(x) < 0 \text{ for each } x \in \Sigma_{\lambda} \text{ and } i \in \{1, \dots, m\}\},$$

$$\mu_1 = \inf_{\lambda \in A_1} \lambda.$$
(2.10)

We now claim that $A_1 \neq \emptyset$. Let $i \in \{1, ..., m\}$ and $\lambda \in [1/2, 1)$ such that λ is sufficiently close to 1. Then we can easily see $v_{\lambda}^i(x) \leq 0$ for $x \in \partial \Sigma_{\lambda}$ and $v_{\lambda}^i(x) < 0$ for $x \in \operatorname{Int}_{\partial D}(\partial D \cap \partial \Sigma_{\lambda})$ from (2.3). Since $|\Sigma_{\lambda}| \ll 1$ and (2.9) holds, by [2, Corollary 14.1], we have $v_{\lambda}^i \leq 0$ on $\overline{\Sigma_{\lambda}}$. By

$$-\Delta v_{\lambda}^{i}(x) + c_{\lambda}^{ii}(x)v_{\lambda}^{i}(x) \leq -\sum_{j\neq i}^{m} c_{\lambda}^{ij}(x)v_{\lambda}^{j}(x) \leq 0 \quad \text{in } \Sigma_{\lambda} \setminus \{x_{\lambda}\}$$

$$(2.11)$$

and the strong maximum principle, we have $v_{\lambda}^i < 0$ in Σ_{λ} . Since *i* is any element of $\{1, \ldots, m\}$, we have shown $\lambda \in A_1$, which proves the claim.

We now claim that $\mu_1 = 1/2 \in A_1$. Let $i \in \{1, \ldots, m\}$. We have $v_{\mu_1}^i(x) \le 0$ for $x \in \Sigma_{\mu_1}$. Since (2.11) holds with $\lambda = \mu_1$ and $v_{\mu_1}^i(x) < 0$ for $x \in \operatorname{Int}_{\partial D}(\partial \Sigma_{\mu_1} \cap \partial D)$ from (2.3), by the strong maximum principle, we have $v_{\mu_1}^i(x) < 0$ for $x \in \Sigma_{\mu_1}$. Since i is an arbitrary element of $\{1, \ldots, m\}$, we have $\mu_1 \in A_1$. We will show $\mu_1 = 1/2$. Suppose not, namely $\mu_1 > 1/2$. Again let $i \in \{1, \ldots, m\}$. Let *G* be an open set such that $\overline{G} \subset \Sigma_{\mu_1}$ and $|\Sigma_{\mu_1} \setminus \overline{G}| \ll 1$. We have $\max_{x \in \overline{G}} v_{\mu_1}^i(x) < 0$. Let $0 < \varepsilon \ll 1$. Then we have $\max_{x \in \overline{G}} v_{\mu_1 - \varepsilon}^i(x) < 0$ and $|\Sigma_{\mu_1 - \varepsilon} \setminus \overline{G}| \ll 1$. Since (2.9) holds with $\lambda = \mu_1 - \varepsilon$ and $v_{\mu_1 - \varepsilon}^i(x) \le 0$ for $x \in \partial (\Sigma_{\mu_1 - \varepsilon} \setminus \overline{G})$, we have $v_{\mu_1 - \varepsilon}^i(x) \le 0$ for $x \in \Sigma_{\mu_1 - \varepsilon}$ by [2, Corollary 14.1]. From $v_{\mu_1 - \varepsilon}^i(x) < 0$ for $x \in (\operatorname{Int}_{\partial D}(\partial \Sigma_{\mu_1 - \varepsilon} \cap \partial D)) \cup \partial G$ and the strong maximum principle, we have $v_{\mu_1 - \varepsilon}^i(x) < 0$ for $x \in \Sigma_{\mu_1 - \varepsilon}$. Since i is an arbitrary element of $\{1, \ldots, m\}$, we have $\mu_1 - \varepsilon \in A_1$. This is a contradiction. Hence $\mu_1 = 1/2 \in A_1$.

We now set

$$A_{2} := \{\lambda \in (0, 1/2) : v_{\lambda}^{l}(x) < 0 \text{ for each } x \in \Sigma_{\lambda} \text{ and } i \in \{1, \dots, m\}\},$$

$$\mu_{2} := \inf_{\lambda \in A_{2}} \lambda.$$
(2.12)

We now claim that $A_2 \neq \emptyset$. Let $i \in \{1, ..., m\}$. We note that $x_{1/2} = (1, 0)$. Let G be an open set such that $\overline{G} \subset \Sigma_{1/2}$ and $|\Sigma_{1/2} \setminus G| \ll 1$. From $1/2 \in A_1$ and $\overline{G} \subset \Sigma_{1/2}$, we have $\max_{x \in \overline{G}} v_{1/2}^i(x) < 0$. Let $\lambda \in (0, 1/2)$ such that λ is sufficiently close to 1/2. We note $|\Sigma_{\lambda} \setminus \overline{G}| \ll 1$ and x_{λ} is close to (1, 0). We choose a sufficiently small open neighborhood U of x_{λ} with $\overline{U} \subset \Sigma_{\lambda}$, and we set $H = G \cup U$. Then we have $v_{\lambda}^i(x) < 0$ for $x \in \overline{H}$, $v_{\lambda}^i(x) \leq 0$ for $x \in \partial \Sigma_{\lambda} \cup \partial H$ and $|\Sigma_{\lambda} \setminus \overline{H}| \ll 1$. Since (2.9) holds on $\Sigma_{\lambda} \setminus \overline{H}$, by [2, Corollary 14.1], we have $v_{\lambda}^i \leq 0$ on Σ_{λ} . From (2.11) and the strong maximum principle, we have $v_{\lambda}^i < 0$ on Σ_{λ} . Since *i* is an arbitrary element of $\{1, \ldots, m\}$, we have shown $\lambda \in A_2$.

Recalling that u is of class C^n at the origin, arguing exactly as in [19, Lemma 4] we get

$$\frac{\partial \left(\tilde{u}^{i} \circ h_{\mu_{2}}\right)}{\partial x_{1}}(x_{\mu_{2}}) = 0 \quad \text{for each } i = 1, \dots, m.$$

$$(2.13)$$

We now claim that $\mu_2 = 0$. Suppose not. Let $i \in \{1, ..., m\}$. Then we have $\mu_2 \in (0, 1/2)$ by the previous claim and we can see $v_{\mu_2}^i \leq 0$ on Σ_{μ_2} . We will show $v_{\mu_2}^i < 0$ on $\Sigma_{\mu_2} \setminus \{x_{\mu_2}\}$. We have $v_{\mu_2}^i(x) < 0$ for $x \in \text{Int}_{\partial D}(\partial \Sigma_{\mu_2} \cap \partial D)$ from (2.3).

By (2.11) with $\lambda = \mu_2$ and the strong maximum principle, we have $v_{\mu_2}^i < 0$ on $\Sigma_{\mu_2} \setminus \{x_{\mu_2}\}$. Next, we will show $v_{\mu_2}^i(x_{\mu_2}) < 0$. Suppose $v_{\mu_2}^i(x_{\mu_2}) < 0$ does not hold, i.e., $v_{\mu_2}^i(x_{\mu_2}) = 0$. Let $v_1 = (-1, 0)$ and $v_2 = (1, 0)$. From (2.13), we have

$$\frac{\partial v_{\mu_2}^i}{\partial v_1}(x_{\mu_2}) = -\frac{\partial \widetilde{u}^i}{\partial x_1}(x_{\mu_2}) + \frac{\partial (\widetilde{u}^i \circ h_{\mu_2})}{\partial x_1}(x_{\mu_2}) = -\frac{\partial \widetilde{u}^i}{\partial x_1}(x_{\mu_2}),$$
$$\frac{\partial v_{\mu_2}^i}{\partial v_2}(x_{\mu_2}) = \frac{\partial \widetilde{u}^i}{\partial x_1}(x_{\mu_2}) - \frac{\partial (\widetilde{u}^i \circ h_{\mu_2})}{\partial x_1}(x_{\mu_2}) = \frac{\partial \widetilde{u}^i}{\partial x_1}(x_{\mu_2}).$$

By Hopf's lemma, we obtain

$$-\frac{\partial \widetilde{u}^i}{\partial x_1}(x_{\mu_2}) < 0 \quad \text{and} \quad \frac{\partial \widetilde{u}^i}{\partial x_1}(x_{\mu_2}) < 0,$$

which is a contradiction. So we have shown $v_{\mu_2}^i(x_{\mu_2}) < 0$. Thus we have $v_{\mu_2}^i < 0$ on Σ_{μ_2} . Since *i* is an arbitrary element of $\{1, \ldots, m\}$, we have $\mu_2 \in A_2$. Again let $i \in \{1, \ldots, m\}$. We choose an open set *G* such that $\overline{G} \subset \Sigma_{\mu_2}$ and $|\Sigma_{\mu_2} \setminus \overline{G}| \ll 1$. We have $\max_{\overline{G}} v_{\mu_2}^i < 0$. Let $0 < \varepsilon \ll 1$. Then we have $|\Sigma_{\mu_2-\varepsilon} \setminus \overline{G}| \ll 1$ and $\max_{\overline{G}} v_{\mu_2-\varepsilon}^i < 0$. Since (2.9) holds with $\lambda = \mu_2 - \varepsilon$, by [2, Corollary 14.1], we have $v_{\mu_2-\varepsilon}^i(x) \le 0$ for $x \in \Sigma_{\mu_2-\varepsilon} \setminus \overline{G}$. By (2.11) with $\lambda = \mu_2 - \varepsilon$ and the strong maximum principle, we have $v_{\mu_2-\varepsilon}^i(x) < 0$ for $x \in \Sigma_{\mu_2-\varepsilon} \setminus \overline{G}$. Hence we have shown $v_{\mu_2-\varepsilon}^i(x) < 0$ for $x \in \Sigma_{\mu_2-\varepsilon}$. Since *i* is an arbitrary element of $\{1, \ldots, m\}$, we have $\mu_2 - \varepsilon \in A_2$, which is a contradiction. Therefore we obtain $\mu_2 = 0$.

We can finally conclude the proof of Theorem 1.1. Let $i \in \{1, ..., m\}$. By the conclusions above, we can infer that \tilde{u}^i is radially symmetric and $\frac{\partial \tilde{u}^i}{\partial r}(|x|) < 0$ for $r = |x| \in (0, 1)$. From the definition of \tilde{u}^i , we can find u^i is also radially symmetric and $\frac{\partial u^i}{\partial r}(|x|) < 0$.

3. Proof of Theorem 1.2

Let us first prove assertion (I) of Theorem 1.2. Assume that (u, v) is an *n*-mode solution to system (1.2) such that $n \ge 1 + \lceil \alpha/2 \rceil$. Then, we may choose $\hat{n}, m \in \mathbb{N}$ such that $m/\hat{n} \in \mathbb{N}, (\alpha + 2)\hat{n} \le 2n < 2(\alpha + 2)\hat{n}$ and

$$m > \max\left\{\frac{n\hat{n}}{(\alpha+2)\hat{n}-n}, \frac{2n}{\alpha+2}\right\}.$$

Setting $\hat{u}(r, \theta) := u(r^{m/n}, m\theta/n)$ and $\hat{v}(r, \theta) := v(r^{m/n}, m\theta/n)$, it is readily seen that \hat{u} and \hat{v} are both $\hat{m} = m/\hat{n}$ -mode and solve, in $D \setminus \{0\}$, the system

$$\begin{cases} \Delta \hat{u} + \frac{2pm^2}{(p+q)n^2} |x|^{\frac{m(\alpha+2)-2n}{n}} \hat{u}^{p-1} \hat{v}^q = 0 & \text{in } D \setminus \{0\}, \\ \Delta \hat{v} + \frac{2pm^2}{(p+q)n^2} |x|^{\frac{m(\alpha+2)-2n}{n}} \hat{u}^p \hat{v}^{q-1} = 0 & \text{in } D \setminus \{0\}, \\ \hat{u} > 0, \quad \hat{v} > 0 & \text{in } D \setminus \{0\}, \\ \hat{u} = \hat{v} = 0 & \text{on } \partial D. \end{cases}$$

We need to show that (\hat{u}, \hat{v}) is a solution of the corresponding system on *D*, namely

$$\begin{cases} \Delta \hat{u} + \frac{2pm^2}{(p+q)n^2} |x|^{\frac{m(\alpha+2)-2n}{n}} \hat{u}^{p-1} \hat{v}^q = 0 \quad \text{in } D, \\ \Delta \hat{v} + \frac{2pm^2}{(p+q)n^2} |x|^{\frac{m(\alpha+2)-2n}{n}} \hat{u}^p \hat{v}^{q-1} = 0 \quad \text{in } D. \end{cases}$$
(3.1)

To this aim, let $\varphi \in C_c^{\infty}(D)$ a function and let $\varepsilon \in (0, 1)$. Then, if D_{ε} denotes the ball centered at zero with radius ε , we get

$$\begin{split} 0 &= \int_{D\setminus D_{\varepsilon}} \Delta \hat{u}\varphi + \frac{2pm^2}{(p+q)n^2} \int_{D\setminus D_{\varepsilon}} |x|^{\frac{m(\alpha+2)-2n}{n}} \hat{u}^{p-1} \hat{v}^q \varphi \\ &= -\int_{\partial D_{\varepsilon}} \frac{\partial \hat{u}}{\partial r} \varphi dS - \int_{D\setminus D_{\varepsilon}} \nabla \hat{u} \nabla \varphi + \frac{2pm^2}{(p+q)n^2} \int_{D\setminus D_{\varepsilon}} |x|^{\frac{m(\alpha+2)-2n}{n}} \hat{u}^{p-1} \hat{v}^q \varphi, \\ 0 &= \int_{D\setminus D_{\varepsilon}} \Delta \hat{v}\varphi + \frac{2pm^2}{(p+q)n^2} \int_{D\setminus D_{\varepsilon}} |x|^{\frac{m(\alpha+2)-2n}{n}} \hat{u}^p \hat{v}^{q-1} \varphi \\ &= -\int_{\partial D_{\varepsilon}} \frac{\partial \hat{v}}{\partial r} \varphi dS - \int_{D\setminus D_{\varepsilon}} \nabla \hat{v} \nabla \varphi + \frac{2pm^2}{(p+q)n^2} \int_{D\setminus D_{\varepsilon}} |x|^{\frac{m(\alpha+2)-2n}{n}} \hat{u}^p \hat{v}^{q-1} \varphi. \end{split}$$

Since also $u \in C^1(\overline{D})$, the functions $\frac{\partial u}{\partial r}(r,\theta)$, $\frac{1}{r}\frac{\partial u}{\partial \theta}(r,\theta)$, $\frac{\partial \varphi}{\partial r}(r,\theta)$, $\frac{1}{r}\frac{\partial \varphi}{\partial \theta}(r,\theta)$ are bounded on *D*. From $\overline{u}(r,\theta) = u(r^{\frac{m}{n}}, \frac{m}{n}\theta)$, there exists some positive constant *C* such that

$$\left|\frac{\partial \bar{u}}{\partial r}(r,\theta)\right| \leq Cr^{\frac{m}{n}-1}, \qquad \left|\frac{\partial \bar{u}}{\partial \theta}(r,\theta)\right| \leq Cr,$$

for each $(r, \theta) \in D$. Hence, we have

$$\left| \int_{|\mathbf{x}|=\varepsilon} \frac{\partial \bar{u}}{\partial r} \varphi \, dS \right| \le C \varepsilon^{\frac{m}{n}},$$
$$\left| \int_{\{\varepsilon < |\mathbf{x}|<1\}} \nabla \bar{u} \, \nabla \varphi - \int_{D} \nabla \bar{u} \, \nabla \varphi \right| \le C \varepsilon^{\frac{m}{n}+1} + C \varepsilon^{2}$$

Hence, letting $\varepsilon \to +0$, we conclude that (\hat{u}, \hat{v}) is a weak (and hence a strong) solution to (3.1). Since $(m(\alpha + 2) - 2n)/n \ge \hat{m} - 1$, it follows that $\hat{u}, \hat{v} \in C^{\hat{m}}(\overline{D})$. Furthermore, since $(\alpha + 2)\hat{n} \le 2n$ the map $r \mapsto r^{2-2\hat{m}+(m(\alpha+2)-2n)/n}$ is nonincreasing. In turn, by applying Theorem 1.1, it follows that \hat{u} and \hat{v} are radially symmetric and hence u and v are radially symmetric, concluding the first part of the proof.

We now come to the proof of assertion (III). We set $H_n = \{u \in H_0^1(D) : u \text{ is } n \text{-mode}\}$ for all $n \in \mathbb{N}$ and $H_\infty = \{u \in H_0^1(D) : u \text{ is radially symmetric}\}$. For any $p, q > 1, \alpha \ge 0$ and $n \in \mathbb{N} \cup \{\infty\}$, set

$$S_{\alpha,p,q,n} = \inf\{R_{\alpha,p,q}(u,v) : u, v \in H_n \setminus \{0\}\}$$

From the proof of [23, Proposition 2.5], we can find

$$S_{\alpha,p,q,\infty} \ge S_{0,p,q,1} \left(\frac{\alpha+2}{2}\right)^{1+\frac{2}{p+q}}.$$
(3.2)

Next, let φ be any element of $C_0^{\infty}(D)$. Since we can consider $\varphi \in C_0^{\infty}(\mathbb{R}^2)$ by the trivial extension, we can define $\varphi_{\alpha} \in C_0^{\infty}(D)$ by $\varphi_{\alpha}((x_1, x_2)) = \varphi(\alpha(x_1 - (1 - 1/\alpha)), \alpha x_2)$ for $(x_1, x_2) \in D$. We set $D_1 = D$ and

 $D_n = \{ (r, \theta) : 0 < r < 1, -\pi/n < \theta < \pi/n \} \text{ for } n \in \mathbb{N} \setminus \{1\}.$

For each $n \in \mathbb{N}$ and $\alpha > 0$ with supp $\varphi_{\alpha} \subset D_n$, we will show

$$S_{\alpha,p,q,n} \le S_{0,p,q,1} n^{1-\frac{2}{p+q}} \alpha^{\frac{4}{p+q}} \left(\frac{\alpha}{\alpha-2}\right)^{\frac{2\alpha}{p+q}}.$$
(3.3)

We define $P_n : D \to D$ by $P_n(r, \theta) = (r, \theta + 2\pi/n)$ for $(r, \theta) \in [0, 1) \times \mathbb{R}$. We set $\widetilde{\varphi}(x) = \varphi_\alpha(x) + \varphi_\alpha(P_n(x)) + \dots + \varphi_\alpha(P_n^{n-1}(x))$ for $x \in D$. Since we have

$$\int_{D} |\nabla \varphi_{\alpha}|^{2} = \int_{D} |\nabla \varphi|^{2}$$

and

$$\int_{D} |x|^{\alpha} |\varphi_{\alpha}|^{p} |\varphi_{\alpha}|^{q} \geq \alpha^{-2} \left(1 - \frac{2}{\alpha}\right)^{\alpha} \int_{D} |\varphi|^{p} |\varphi|^{q},$$

we obtain

$$S_{\alpha,p,q,n} \leq R_{\alpha,p,q}(\widetilde{\varphi},\widetilde{\varphi}) \leq \frac{n \int_{D} (|\nabla \varphi|^{2} + |\nabla \varphi|^{2})}{\left(n\alpha^{-2} \left(1 - \frac{2}{\alpha}\right)^{\alpha} \int_{D} |\varphi|^{p} |\varphi|^{q}\right)^{\frac{2}{p+q}}}.$$

Since $\varphi \in C_0^{\infty}(D)$ is arbitrary, we have shown (3.3). From (3.2) and (3.3), we can see that $n \leq n_{\alpha}$ is a sufficient condition for $S_{\alpha,p,q,n} < S_{\alpha,p,q,\infty}$. We will show that if n > 1 and $S_{\alpha,p,q,n} < S_{\alpha,p,q,\infty}$ then $S_{\alpha,p,q,1} < \cdots < S_{\alpha,p,q,n}$. Let n > 1 and $S_{\alpha,p,q,n} < S_{\alpha,p,q,\infty}$. We can choose $u, v \in H_n \setminus \{0\}$ such that $R_{\alpha,p,q}(u, v) = S_{\alpha,p,q,n}$ and $u, v \geq 0$. We note that $u, v \notin H_{\infty}$ and (u, v) is a positive solution of (1.2). Let $m \in \{1, \ldots, n-1\}$. We define $\overline{u}, \overline{v} \in H_m$ by $\overline{u}(r, \theta) = u(r, m\theta/n)$ and $\overline{v}(r, \theta) = v(r, m\theta/n)$ for $(r, \theta) \in [0, 1) \times \mathbb{R}$. Since we can see

$$\int_{D} |\mathbf{x}|^{\alpha} |\bar{u}|^{p} |\bar{v}|^{q} = \int_{D} |\mathbf{x}|^{\alpha} |u|^{p} |v|^{q},$$
$$\int_{D} |\nabla \bar{u}|^{2} = \int_{0}^{2\pi} \int_{0}^{1} \left(\left| \frac{\partial u}{\partial r} \right|^{2} + \frac{m^{2}}{n^{2}r^{2}} \left| \frac{\partial u}{\partial \theta} \right|^{2} \right) r \, dr d\theta < \int_{D} |\nabla u|^{2}$$

and $\int_D |\nabla \bar{v}|^2 < \int_D |\nabla v|^2$, we have

$$S_{\alpha,p,q,m} \leq R_{\alpha,p,q}(\bar{u},\bar{v}) < R_{\alpha,p,q}(u,v) = S_{\alpha,p,q,n}.$$

By a similar argument, we conclude that $S_{\alpha,p,q,1} < \cdots < S_{\alpha,p,q,n}$. Hence we infer that if $S_{\alpha,p,q,n} < S_{\alpha,p,q,\infty}$, then for each $\ell = 1, \ldots, n$, there exists a nonradial positive solution $(u_{\ell}, v_{\ell}) \in H_{\ell} \times H_{\ell}$ of (1.2) satisfying $R_{\alpha,p,q}(u_{\ell}, v_{\ell}) = S_{\alpha,p,q,\ell}$. We set the number in (1.4) as $\eta(\alpha, p, q)$. For a fixed $\alpha \in (2, \infty)$, we have $\eta(\alpha, p, q) \rightarrow 1 + \alpha/2$ as $p + q \rightarrow \infty$, which yields (i). For a fixed $p, q \in (1, \infty)$, we have $\eta(\alpha, p, q) \rightarrow \infty$ as $\alpha \rightarrow \infty$, yielding (ii). Hence, we finish the proof of Theorem 1.2.

Acknowledgments

The first author was partially supported by the Grant-in-Aid for Scientific Research (C) (No. 21540214) from Japan Society for the Promotion of Science. The second author was partially supported by 2009 Italian MIUR project: "Variational and Topological Methods in the Study of Nonlinear Phenomena".

References

- C.O. Alves, D.C. de Morais Filho, M.A.S. Souto, On systems of elliptic equations involving subcritical or critical Sobolev exponents, Nonlinear Anal. Ser. A: Theory Methods 42 (5) (2000) 771–787.
- [2] J. Busca, B. Sirakov, Harnack type estimates for nonlinear elliptic systems and applications, Ann. Inst. H. Poincaré Anal. Non Linéaire 21 (5) (2004) 543-590.
- [3] L. Damascelli, F. Gladiali, F. Pacella, A symmetry result for semilinear cooperative elliptic systems, Contemp. Math. (in press).
- [4] L. Damascelli, F. Gladiali, F. Pacella, Symmetry results for cooperative elliptic systems in unbounded domains, Preprint.
- [5] L. Damascelli, F. Pacella, Symmetry results for cooperative elliptic systems via linearization, Preprint.
- [6] D.G. de Figueiredo, Monotonicity and symmetry of solutions of elliptic systems in general domains, NoDEA Nonlinear Differential Equations Appl. 1 (2) (1994) 119–123.
- [7] D.G. de Figueiredo, Semilinear elliptic systems: existence, multiplicity, symmetry of solutions, in: Handbook of Differential Equations: Stationary Partial Differential Equations. Vol. V, 2008, pp. 1–48.
- [8] M. Ghergu, V.D. Rădulescu, Nonlinear PDEs: Mathematical Models in Biology, Chemistry and Population Genetics, in: Springer Monographs in Mathematics, Springer, Heidelberg, 2012, With a foreword by Viorel Barbu.
- [9] B. Gidas, W.M. Ni, L. Nirenberg, Symmetry and related properties via the maximum principle, Comm. Math. Phys. 68 (3) (1979) 209-243.
- [10] P. Han, High-energy positive solutions for a critical growth Dirichlet problem in noncontractible domains, Nonlinear Anal. 60 (2) (2005) 369–387.
- [11] P. Han, Multiple positive solutions of nonhomogeneous elliptic systems involving critical Sobolev exponents, Nonlinear Anal. 64 (4) (2006) 869–886.
 [12] M. Hénon, Numerical experiments on the stability of spherical stellar systems, Astron. Astrophys. 24 (1973) 229–238.
- [12] M. Helloh, Kulherkar experiments on the stability of spherical stellar systems, Astron. Astrophys. 24 (1973) 223–236.
 [13] S. Kesavan, F. Pacella, Symmetry of solutions of a system of semilinear elliptic equations, Adv. Math. Sci. Appl. 9 (1) (1999) 361–369.
- [14] E. Montefusco, B. Pellacci, M. Squassina, Semiclassical states for weakly coupled nonlinear Schrödinger systems, J. Eur. Math. Soc. (JEMS) 10 (1) (2008) 47–71.
- [15] D. Motreanu, V. Rădulescu, Variational and Non-Variational Methods in Nonlinear Analysis and Boundary Value Problems, in: Nonconvex Optimization Applications, vol. 67, Kluwer Pub., Dordrecht, 2003.
- [16] J.D. Murray, Mathematical Biology. II: Spatial Models and Biomedical Applications, third ed., in: Interdisciplinary Applied Mathematics, vol. 18, Springer-Verlag, New York, 2003.
- [17] W.M. Ni, A nonlinear Dirichlet problem on the unit ball and its applications, Indiana Univ. Math. J. 31 (1982) 801-807.
- [18] V.D. Rădulescu, Qualitative Analysis of Nonlinear Elliptic Partial Differential Equations: Monotonicity, Analytic, and Variational Methods, in: Contemporary Mathematics and its Applications, vol. 6, Hindawi Publishing Corporation, New York, 2008.
- [19] N. Shioji, K. Watanabe, Radial symmetry of n-mode positive solutions for semilinear elliptic equations in a disc and its application to the Hénon equation, Topol. Methods Nonlinear Anal. (in press).
- [20] J. Smoller, Shock Waves and Reaction-Diffusion Equations, second ed., in: Grundlehren der Mathematischen Wissenschaften, vol. 258, Springer-Verlag, New York, 1994.
- [21] W.C. Troy, Symmetry properties in systems of semilinear elliptic equations, J. Differential Equations 42 (3) (1981) 400-413.
- [22] Y. Wang, J. Yang, Asymptotic behavior of ground state solution for Henon type systems, Electron. J. Differential Equations 116 (5) (2010) 1-14.
- [23] Y. Wang, J. Yang, Existence and asymptotic behavior of solutions for Hénon type systems, Adv. Nonlinear Stud. (in press).