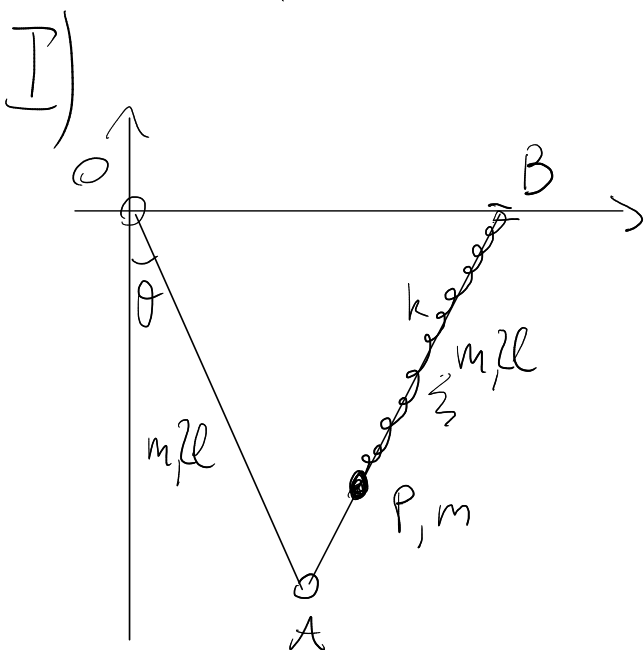


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$$\xi \in [0, 2l] \quad \lambda = \frac{mg}{kl}$$

$$(G_1 - O) = (l \sin \theta, -l \cos \theta)$$

$$\begin{aligned} (G_2 - O) &= (G_2 - A) + (A - O) \\ &= (l \sin \theta, l \cos \theta) + (2l \sin \theta, -2l \cos \theta) \\ &= (3l \sin \theta, -l \cos \theta) \end{aligned}$$

$$\begin{aligned} (P - O) &= (P - A) + (A - O) = ((2l - \xi) \sin \theta, (2l - \xi) \cos \theta) \\ &\quad + (2l \sin \theta, -2l \cos \theta) \\ &= ((4l - \xi) \sin \theta, -\xi \cos \theta) \end{aligned}$$

$$|P - B|^2 = \xi^2$$

$$U = 2mgl \cos \theta + mg \xi \cos \theta - \frac{1}{2} k \xi^2$$

$$\left\{ \begin{aligned} \frac{\partial U}{\partial \xi} &= mg \cos \theta - k \xi \end{aligned} \right.$$

$$\xi = \frac{mg}{k} \cos \theta = \lambda \cos \theta$$

$$\left\{ \begin{aligned} \frac{\partial U}{\partial \theta} &= -2mgl \sin \theta - mg \xi \sin \theta \end{aligned} \right.$$

$$\sin \theta = 0 \quad \theta = 0 \quad \xi = \lambda \quad \text{or} \quad \lambda < 2$$

$$\theta = \pi \quad \xi = -\lambda \quad \text{n. A.}$$

$$-2\cancel{m}gl - \cancel{m}g\xi = 0 \quad \xi = -2l \text{ N.A.}$$

$$P(\lambda l, 0) \quad \text{per } \lambda < 2$$

$$Hl = \begin{bmatrix} -k & -mg \sin \theta \\ -mg \sin \theta & -2mgl \cos \theta - mg \xi \cos \theta \end{bmatrix}$$

$$Hl(P) = \begin{bmatrix} -k & 0 \\ 0 & -2mgl - \lambda mgl \end{bmatrix} \quad \text{STABLE}$$

compare:

$$\xi = 0 \quad \begin{cases} mg \cos \theta \leq 0 \\ -2mgl \sin \theta = 0 \end{cases}$$

$$\theta = 0 \quad \text{no}$$

$$\theta = \pi \quad \text{ok}$$

$(0, \pi)$ pos. eq. compare

$$\xi = 2l \quad \begin{cases} mg \cos \theta - 2kl \geq 0 \\ -2mgl \sin \theta - 2mgl \sin \theta = 0 \end{cases}$$

$$\theta = 0 \quad mg - 2kl \geq 0 \quad \lambda \geq 2$$

$$\theta = \pi \quad -mg - 2kl \geq 0 \quad \text{N.A.}$$

$$(2l, 0) \quad \text{eq. confine per } l \geq 2$$

$$\vec{v}_p = (-\dot{\xi} \sin \theta + (4l - \xi) \dot{\theta} \cos \theta, -\dot{\xi} \cos \theta + \xi \dot{\theta} \sin \theta)$$

$$\begin{aligned} |\vec{v}_p|^2 &= \dot{\xi}^2 + (4l - \xi)^2 \dot{\theta}^2 \cos^2 \theta - 2(4l - \xi) \dot{\xi} \dot{\theta} \sin \theta \cos \theta \\ &\quad - 2\xi \dot{\xi} \dot{\theta} \sin \theta \cos \theta + \xi^2 \dot{\theta}^2 \sin^2 \theta \\ &= \dot{\xi}^2 + 16l^2 \dot{\theta}^2 \cos^2 \theta - 8l\xi \dot{\theta}^2 \cos^2 \theta + \xi^2 \dot{\theta}^2 \cos^2 \theta \\ &\quad - 8l\xi \dot{\xi} \dot{\theta} \sin \theta \cos \theta + 2\xi \dot{\xi} \dot{\theta} \sin \theta \cos \theta \\ &\quad - 2\xi \dot{\xi} \dot{\theta} \sin \theta \cos \theta + \xi^2 \dot{\theta}^2 \sin^2 \theta \\ &= \dot{\xi}^2 + \xi^2 \dot{\theta}^2 + (16l^2 - 8l\xi) \dot{\theta}^2 \cos^2 \theta \\ &\quad - 8l\xi \dot{\xi} \dot{\theta} \sin \theta \cos \theta \end{aligned}$$

$$\vec{v}_{G_2} = (3l\dot{\theta} \cos \theta, -l\dot{\theta} \sin \theta)$$

$$\begin{aligned} |\vec{v}_{G_2}|^2 &= 9l^2 \dot{\theta}^2 \cos^2 \theta + l^2 \dot{\theta}^2 \sin^2 \theta \\ &= 8l^2 \dot{\theta}^2 \cos^2 \theta + l^2 \dot{\theta}^2 \\ &= l^2 \dot{\theta}^2 (1 + 8 \cos^2 \theta) \end{aligned}$$

$$K = \frac{1}{2} J_A \omega^2 + \frac{m}{2} |v_{G_2}|^2 + \frac{1}{2} J_{G_2} \omega^2 + \frac{1}{2} m |v_p|^2$$

$$J_A = \frac{4}{3} m l^2 \quad J_{G_2} = \frac{1}{3} m l^2$$

$$K = \frac{1}{2} \left(\frac{4}{3} m l^2 \dot{\theta}^2 + m l^2 \dot{\theta}^2 (1 + 8 \cos^2 \theta) \right) + \frac{1}{3} m l^2 \dot{\theta}^2$$

$$+ m \dot{\xi}^2 + m \xi^2 \ddot{\theta}^2 + 8ml(2l-\xi) \dot{\theta}^2 \cos^2 \theta - 8ml\xi \dot{\xi} \dot{\theta} \sin \theta \cos \theta)$$

$$= \frac{1}{2} \left(m \dot{\xi}^2 + m \left(\frac{8}{3} + 8 \cos^2 \theta \right) l^2 \dot{\theta}^2 + m \xi^2 \dot{\theta}^2 + 8ml(2l-\xi) \dot{\theta}^2 \cos^2 \theta - 8ml\xi \dot{\xi} \dot{\theta} \sin \theta \cos \theta \right)$$

$$K = \begin{bmatrix} m & -4ml\xi \sin \theta \cos \theta \\ -4ml\xi \sin \theta \cos \theta & m \left(\left(\frac{8}{3} + 8 \cos^2 \theta \right) l^2 + m \xi^2 + 8ml(2l-\xi) \cos^2 \theta \right) \end{bmatrix}$$

$$\text{II}) \quad J_G^Q = \begin{bmatrix} \frac{ml^2}{12} & & \\ & \frac{ml^2}{12} & \\ & & \frac{ml^2}{6} \end{bmatrix} \quad \vec{d} = \left(\frac{l}{\sqrt{2}}, \frac{l}{\sqrt{2}}, 0 \right)$$

$$|d|^2 = l^2 \quad d \otimes d = \begin{bmatrix} \frac{l^2}{2} & \frac{l^2}{2} & 0 \\ \frac{l^2}{2} & \frac{l^2}{2} & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad d^2 I - d \otimes d = \begin{bmatrix} \frac{l^2}{2} & -\frac{l^2}{2} & 0 \\ -\frac{l^2}{2} & \frac{l^2}{2} & 0 \\ 0 & 0 & l^2 \end{bmatrix}$$

$$J_0^Q = J_G^Q + m(d^2 I - d \otimes d) =$$

$$= \begin{bmatrix} \frac{7}{12} m l^2 & -\frac{m l^2}{2} & 0 \\ -\frac{m l^2}{2} & \frac{7}{12} m l^2 & 0 \\ 0 & 0 & \frac{7}{6} m l^2 \end{bmatrix}$$

$$J_G^{a_1} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \frac{m l^2}{12} & 0 \\ 0 & 0 & \frac{m l^2}{12} \end{bmatrix} \quad d = \left(-\frac{l}{2}, \frac{l}{\sqrt{2}}, 0\right)$$

$$d^L = \frac{3}{4} l^2 \quad d \otimes d = \begin{bmatrix} \frac{l^2}{4} & -\frac{l^2}{2\sqrt{2}} & 0 \\ -\frac{l^2}{2\sqrt{2}} & \frac{l^2}{2} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$d^2 I - d \otimes d = \begin{bmatrix} \frac{l^2}{2} & +\frac{l^2}{2\sqrt{2}} & 0 \\ +\frac{l^2}{2\sqrt{2}} & \frac{l^2}{4} & 0 \\ 0 & 0 & \frac{3}{4} l^2 \end{bmatrix}$$

$$J_0^{a_1} = \begin{bmatrix} m \frac{l^2}{2} & +\frac{m l^2}{2\sqrt{2}} & 0 \\ +\frac{m l^2}{2\sqrt{2}} & \frac{m l^2}{3} & 0 \\ 0 & 0 & \frac{5}{6} m l^2 \end{bmatrix}$$

$$\frac{1}{2\sqrt{2}} - \frac{1}{2} =$$

$$\frac{1}{2} \left(\frac{\sqrt{2}}{2} - 1 \right) =$$

$$\frac{\sqrt{2}-2}{4}$$

$$J_0^{a_2} = \begin{bmatrix} \frac{m l^2}{3} & \frac{m l^2}{2\sqrt{2}} & 0 \\ \frac{m l^2}{2\sqrt{2}} & \frac{m l^2}{2} & 0 \\ 0 & 0 & \frac{5}{6} m l^2 \end{bmatrix}$$

$$J_0^{\text{rot}} = \begin{bmatrix} \frac{17}{12}ml^2 & \frac{\sqrt{2}-2}{4}ml^2 & 0 \\ \frac{\sqrt{2}-2}{4}ml^2 & \frac{17}{12}ml^2 & 0 \\ 0 & 0 & \frac{17}{6}ml^2 \end{bmatrix}$$

