

Lectures on

DIFFERENTIAL GEOMETRY AND TOPOLOGY

M
V2

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POINCARÉ LEMMA - NON TRIVIALITY OF SOME HOMOLOGY GROUPS

Let us resume our discussion on de Rham theory

* Poincaré lemma

$$H_{dR}^k(\mathbb{R}^n) = \begin{cases} \mathbb{R} & k=0 \\ \{0\}, & k>0 \end{cases}$$

Proof. The case $k=0$ is easily dealt with: If $df=0 \Rightarrow f=c$ (constant) since \mathbb{R}^n is connected. There are no exact 0-forms (functions) and the conclusion follows.

In general, we construct a sequence of linear maps

$$h_j : \Lambda^{j+1} \rightarrow \Lambda^j$$

such that

$$(1) \quad h_k \circ d + d \circ h_{k-1} = \text{id}_{\Lambda^k}$$

The collection of h_j 's is called "homotopy operator"

$$\dots \rightarrow \Lambda^{k-1} \xrightarrow{d} \Lambda^k \xrightarrow{d} \Lambda^{k+1} \rightarrow \dots$$

Formulae like (1) are extremely important in algebraic topology.

Given $\{h_j\}$, one would find, for $\omega \in \mathbb{Z}^k$

$$h_k d\omega + d \underbrace{h_{k-1} \omega}_{\in \Lambda^{k-1}} = \omega$$

We also observe in advance that the same result and method of proof will hold for star-shaped open sets

i.e.

$$\omega = d(h_{k-1} \omega) \Rightarrow \omega \text{ would be exact.}$$



By linearity, it suffices to define h_{k-1} (say)
on $\omega = g dx^{i_1} \wedge \dots \wedge dx^{i_k}$. So let

$$h_{k-1}(\omega)(\alpha) := \left(\int_0^1 t^{k-1} g(tx) dt \right) \mu,$$

(x₁, ..., x_n)

where

$$\mu = \sum_{j=1}^k (-1)^{j-1} x^{i_j} dx^{i_1} \wedge \dots \overset{\curvearrowleft}{\cancel{dx^{i_j}}} \wedge \dots \wedge dx^{i_k}$$

observe that

$$d\mu = \sum_{j=1}^k (-1)^{j-1} dx^{i_j} \wedge dx^{i_1} \wedge \dots \overset{\curvearrowleft}{\cancel{dx^{i_j}}} \wedge \dots \wedge dx^{i_k}$$

$$= \sum_{j=1}^k dx^{i_1} \wedge \dots \overset{\curvearrowleft}{\cancel{dx^{i_j}}} \wedge \dots = k \cdot dx^{i_1} \wedge \dots \wedge dx^{i_k}$$

example: $\mu = dx_1 dx_2 \wedge dx_3 - dx_2 dx_1 \wedge dx_3 + dx_3 dx_1 \wedge dx_2$

$$\begin{aligned} d\mu &= dx_1 dx_2 \wedge dx_3 - \overset{\curvearrowleft}{dx_2} dx_1 \wedge dx_3 + \overset{\curvearrowleft}{dx_3} dx_1 \wedge dx_2 \\ &= dx_1 dx_2 \wedge dx_3 + dx_1 dx_3 \wedge dx_2 + dx_2 dx_3 \wedge dx_1 \\ &= 3 dx_1 dx_2 \wedge dx_3 \end{aligned}$$

also consider $dx_4 \wedge \frac{1}{3} d\mu = dx_4 \wedge (dx_1 dx_2 \wedge dx_3)$ (say).

then μ' (relative to \uparrow) is

$$\begin{aligned} \mu' &= dx_4 \wedge dx_1 dx_2 \wedge dx_3 - dx_2 dx_4 \wedge dx_1 dx_3 + dx_2 dx_4 \wedge dx_1 dx_3 \\ &\quad - dx_3 dx_4 \wedge dx_1 dx_2 = dx_4 (dx_1 dx_2 \wedge dx_3) \\ &\quad - dx_4 \wedge \mu \end{aligned}$$

This will be needed soon

① Let us compute

$$\begin{aligned}
 \boxed{d(h_{\alpha_{k-1}}(\omega))(\alpha)} &= d \left[\left(\int_0^1 t^{k-1} g(t\alpha) dt \right) \mu \right] = \\
 &= d \left(\int_0^1 t^{k-1} g(t\alpha) dt \right) \wedge \mu + \left\{ \int_0^1 t^{k-1} g(t\alpha) dt \right\} \cdot d\mu \\
 &= \sum_{j=1}^n \left\{ \int_0^1 t^{k-1} \underbrace{t}_{\stackrel{\sim}{\rightarrow}} \cdot t \frac{\partial g}{\partial x_j}(t\alpha) dt \right\} dx_j \wedge \mu \\
 &\quad + \left(\int_0^1 t^{k-1} g(t\alpha) dt \right) \cdot \underbrace{dk \wedge da_1 \wedge \dots \wedge da_k}_{\text{da}_1 \wedge \dots \wedge da_k} \\
 &= \sum_{j=1}^n \left(\int_0^1 t^k \frac{\partial g}{\partial x_j}(t\alpha) dt \right) dx_j \wedge \mu \\
 &\quad + k \cdot \left(\int_0^1 t^{k-1} g(t\alpha) dt \right) \underbrace{dx_1 \wedge \dots \wedge da_k}_{\text{da}_1 \wedge \dots \wedge da_k}
 \end{aligned}$$

② Now compute

$$\begin{aligned}
 h_K(d\omega)(\alpha) &= h_K \left[\sum_{j=1}^n \frac{\partial g}{\partial x_j} dx^j \wedge da_1 \wedge \dots \wedge da_k \right] \\
 &= \sum_{j=1}^n \left(\int_0^1 t^k \frac{\partial g}{\partial x_j}(t\alpha) dt \right) \left[\underbrace{dx^j \wedge da_1 \wedge \dots \wedge da_k}_{\text{da}_1 \wedge \dots \wedge da_k} - da^j \wedge \mu \right] \\
 &\quad \text{cf. the calculation on the preceding page}
 \end{aligned}$$

Then

$$\textcircled{1} + \textcircled{2} = (d \circ h_{k-1} + h_k \circ d)(\omega)(\alpha) =$$

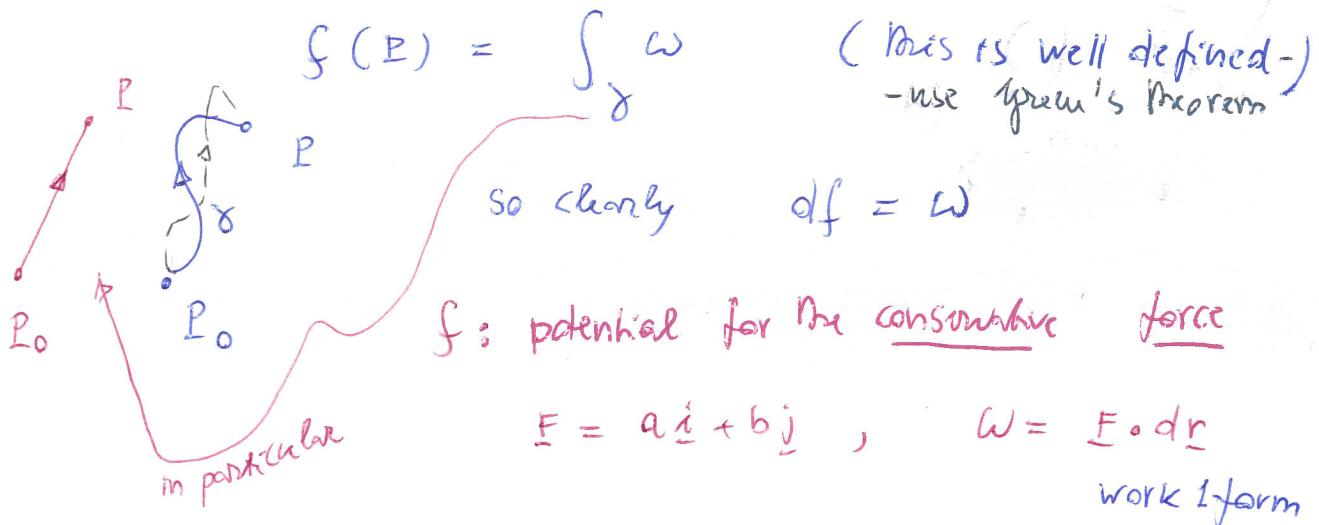
$$\begin{aligned}
 & \sum_{j=1}^n \left[\int_0^1 t^{k-1} \frac{\partial g}{\partial x_j}(tx) dt \right] \left\{ dx^i \wedge \dots \wedge dx^{i_k} - dx^{i_1} \wedge \dots \wedge dx^{i_k} \right\} \\
 & + \left(n \int_0^1 t^{k-1} g(tx) dt \right) dx^{i_1} \wedge \dots \wedge dx^{i_k} \\
 & = \left(\int_0^1 t^{k-1} \underbrace{\sum_{j=1}^n x_j \frac{\partial g}{\partial x_j}(tx)}_{\frac{dg}{dt}(tx)} dt \right) dx^{i_1} \wedge \dots \wedge dx^{i_k} \\
 & + \left(\int_0^1 \underbrace{nt^{k-1}}_{\frac{dt^k}{dt}} g(tx) dt \right) dx^{i_1} \wedge \dots \wedge dx^{i_k} \\
 & = \left(\int_0^1 \frac{d(t^k g)}{dt} dt \right) dx^{i_1} \wedge \dots \wedge dx^{i_k} \\
 & = \left(t^k g(tx) \Big|_0^1 \right) dx^{i_1} \wedge \dots \wedge dx^{i_k} \\
 & = g(\alpha) dx^{i_1} \wedge \dots \wedge dx^{i_k} = \omega \quad \square
 \end{aligned}$$

Comment on the definition of $\{h_k\}$

For a closed 1-form (on \mathbb{R}^2 , say) $\omega = adx + bdy$

($d\omega = 0 \Leftrightarrow \frac{\partial b}{\partial x} - \frac{\partial a}{\partial y} = 0$), exactness is

proved by taking



The construction of $\{h_k\}$ generalizes precisely this idea.

The de Rham group are non-trivial in general and actually detect topological properties of the underlying manifold. Let us discuss some simple examples, coming from physics.

1. $\mathbb{R}^2 - \{(0,0)\}$ Consider the "angular form"

$$\omega = -\frac{y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy$$

It may be written as "mixed formalism"

$$\omega = \frac{i \underline{r} \cdot d\underline{r}}{\|\underline{r}\|^2} = \underline{B} \cdot d\underline{r}$$

$\underline{r} = (x, y)$
 $d\underline{r} = (dx, dy)$

$\int i$ $i = \text{rotation}$

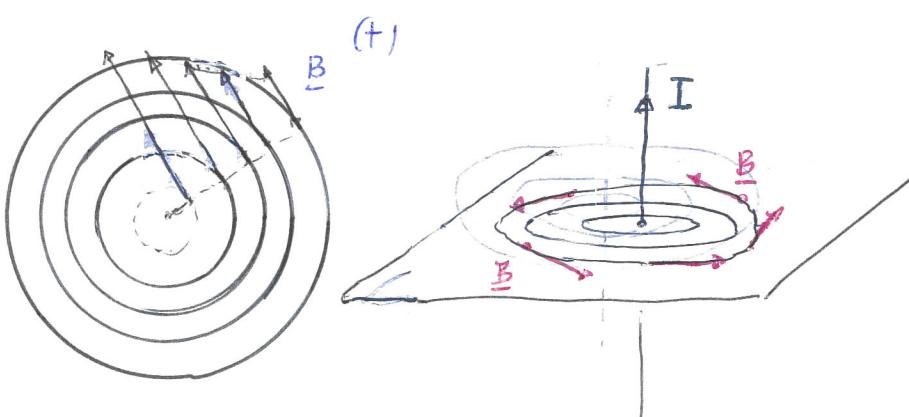
physically, ω

is the element of Circulation $i \equiv$ counterclockwise rotation by $\frac{\pi}{2}$

of the magnetic field determined

by a rectilinear wire wherein an electric current flows

(Biot-Savart law)



$$\|\underline{B}\| \sim \frac{1}{r}$$

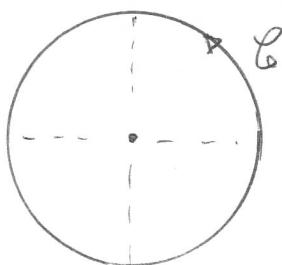
(+) or Σ , see below

1'. In fluid mechanics, $\underline{B} \equiv \underline{\omega}$ is
 the velocity field of an irrotational perfect fluid
 $(\text{d}\omega = 0 \Leftrightarrow \text{curl } \underline{\omega} = 0)$ on $\mathbb{R}^2 \setminus \{(0,0)\}$
 notice that $\text{div } \underline{\omega} = 0$)

possessing a vortex at the origin (some picture)

* Let us then show that $H^2(\mathbb{R}^2 \setminus \{(0,0)\})$ is non-trivial

(later on we shall see that indeed this group is \mathbb{R})



Take, for instance, the unit circle
 $x^2 + y^2 = 1$, oriented counterclockwise

Then an easy calculation shows that

$$\int_C \omega = 2\pi$$

But, if ω were exact, $\omega = df$, then we would have had, instead:

$$\int_C \omega = \int_C df = 0$$

i.e. a contradiction.

2. Let us now check that

$$H^2(\mathbb{R}^3 \setminus \{(0,0,0)\}) \text{ is non-trivial}$$

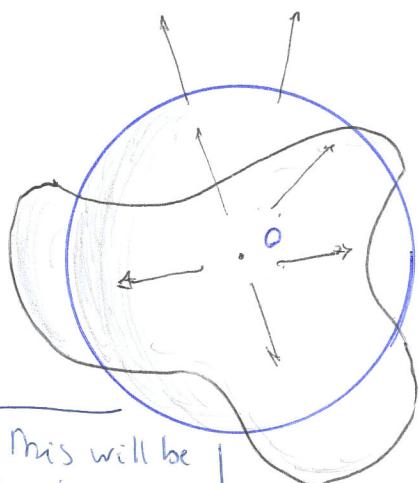
(indeed, it is \mathbb{R})

("Gauss' law" $\operatorname{div} \underline{E} = \rho$)
in electrostatics

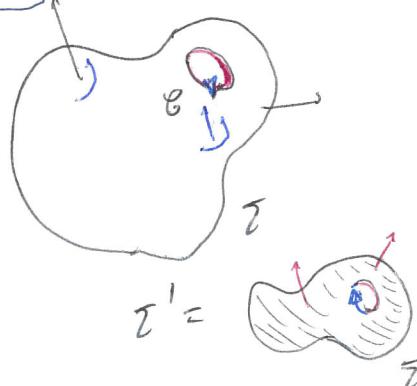
Let \underline{E} be the flux 2-form of $\underline{E} = \frac{\underline{r}}{\|\underline{r}\|^3}$
i.e. electric field generated by a point charge located at the origin

$$\underline{E} = \frac{x}{(x^2+y^2+z^2)^{3/2}} dy_1 dz + \frac{y}{(x^2+y^2+z^2)^{3/2}} dz_1 dx + \frac{z}{(x^2+y^2+z^2)^{3/2}} dx_1 dy$$

$$(\underline{E} = \underline{E} \cdot d\underline{o} = \underline{E} \cdot \underline{n} d\sigma)$$



All this will be
better formalised
later on



one has $d\underline{E} = 0$

(i.e. $\operatorname{div} \underline{E} = 0$: \underline{E} is "Solenoidal")

one has

$$\int_{\Sigma} \underline{E} = \iint_{\Sigma} \underline{E} \cdot \underline{n} d\sigma = 4\pi$$

take e.g. a sphere centred at o

Integral of a 2-form,
we shall formalise it later on

Σ =
closed oriented surface
surrounding o

If \underline{E} were exact, then

$$\underline{E} = d\underline{a}, \text{ or } \underline{E} = \operatorname{curl} \underline{A}$$

$$\text{But } \iint_{\Sigma} \operatorname{curl} \underline{A} \cdot \underline{n} d\sigma = \dots \quad (\text{Stokes})$$

$\int_{\Sigma} \underline{A} \cdot d\underline{r}$, which goes to zero
as \mathcal{G} shrinks to a point.